AC STEADY-STATE ANALYSIS

LEARNING GOALS

SINUSOIDS
Review basic facts about sinusoidal signals

SINUSOIDAL AND COMPLEX FORCING FUNCTIONS
Behavior of circuits with sinusoidal independent sources and modeling of sinusoids in terms of complex exponentials

PHASORS
Representation of complex exponentials as vectors. It facilitates steady-state analysis of circuits.

IMPEDANCE AND ADMITANCE
Generalization of the familiar concepts of resistance and conductance to describe AC steady state circuit operation

PHASOR DIAGRAMS
Representation of AC voltages and currents as complex vectors

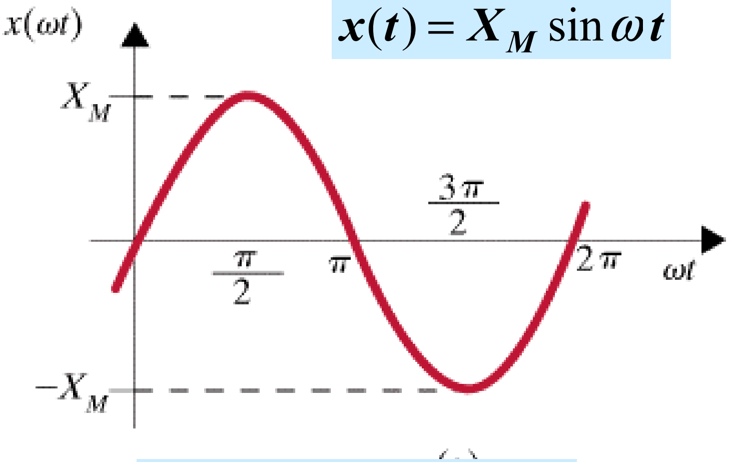
BASIC AC ANALYSIS USING KIRCHHOFF LAWS

ANALYSIS TECHNIQUES
Extension of node, loop, Thevenin and other techniques

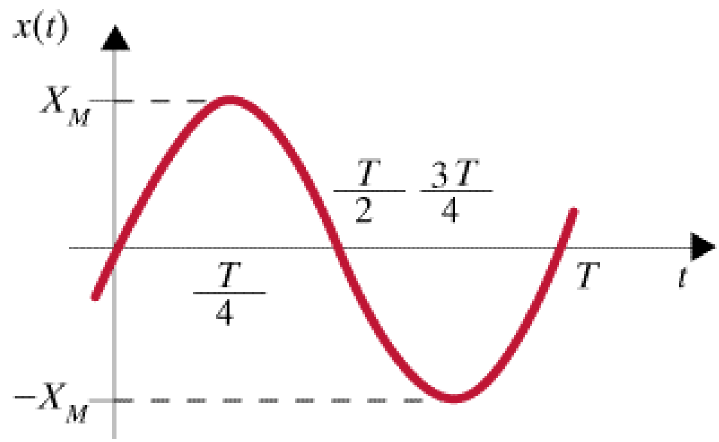
GEAUX

SINUSOIDS

$x(t) = X_M \sin \omega t$



Adimensional plot



As function of time

X_M = amplitude or maximum value

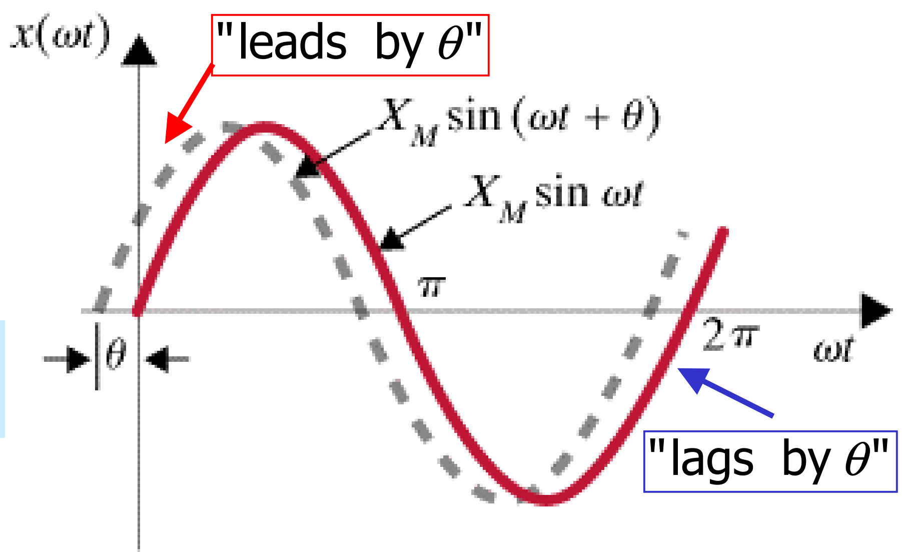
ω = angular frequency (rads/sec)

ωt = argument (radians)

$T = \frac{2\pi}{\omega}$ = Period $\Rightarrow x(t) = x(t+T), \forall t$

$f = \frac{1}{T} = \frac{\omega}{2\pi}$ = frequency in Hertz (cycle/sec)

$\omega = 2\pi f$



BASIC TRIGONOMETRY

ESSENTIAL IDENTITIES

$$\sin(\alpha+\beta)=\sin\alpha\cos\beta+\cos\alpha\sin\beta$$

$$\cos(\alpha+\beta)=\cos\alpha\cos\beta-\sin\alpha\sin\beta$$

$$\sin(-\alpha)=-\sin\alpha$$

$$\cos(-\alpha)=\cos\alpha$$

SOME DERIVED IDENTITIES

$$\sin(\alpha-\beta)=\sin\alpha\cos\beta-\cos\alpha\sin\beta$$

$$\cos(\alpha-\beta)=\cos\alpha\cos\beta+\sin\alpha\sin\beta$$

$$\sin\alpha\cos\beta=\frac{1}{2}\sin(\alpha+\beta)+\frac{1}{2}\sin(\alpha-\beta)$$

$$\cos\alpha\cos\beta=\frac{1}{2}\cos(\alpha+\beta)+\frac{1}{2}\cos(\alpha-\beta)$$

APPLICATIONS

$$\cos\omega t=\sin(\omega t+\frac{\pi}{2})$$

$$\sin\omega t=\cos(\omega t-\frac{\pi}{2})$$

$$\cos\omega t=-\cos(\omega t\pm\pi)$$

$$\sin\omega t=-\sin(\omega t\pm\pi)$$

RADIANS AND DEGREES

2π radians = 360 degrees

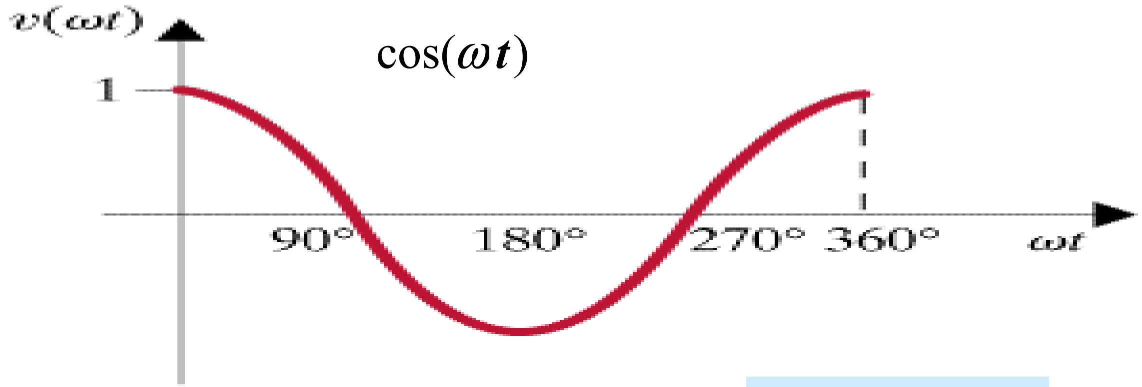
$$\theta(\text{rads})=\frac{180}{\pi}\theta\ (\text{degrees})$$

ACCEPTED EE CONVENTION

$$\sin(\omega t+\frac{\pi}{2})=\sin(\omega t+90°)$$

GEAUX

LEARNING EXAMPLE

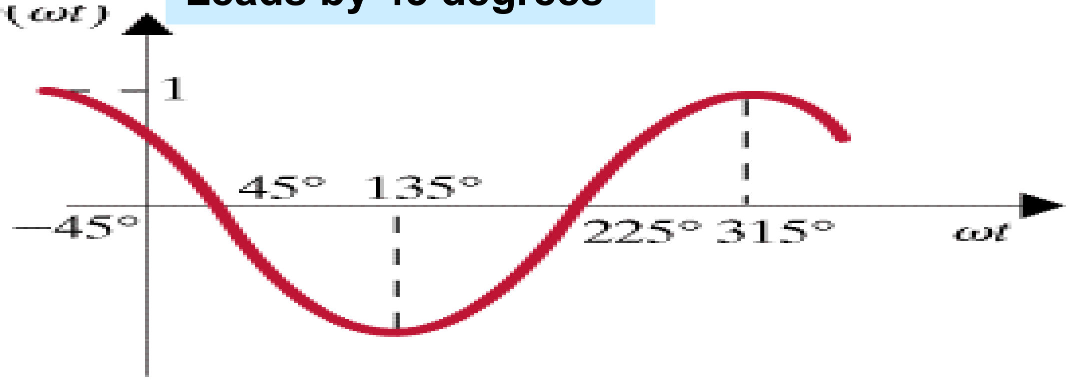


Lags by 315

Leads by 45 degrees

$\cos(\omega t + 45°)$

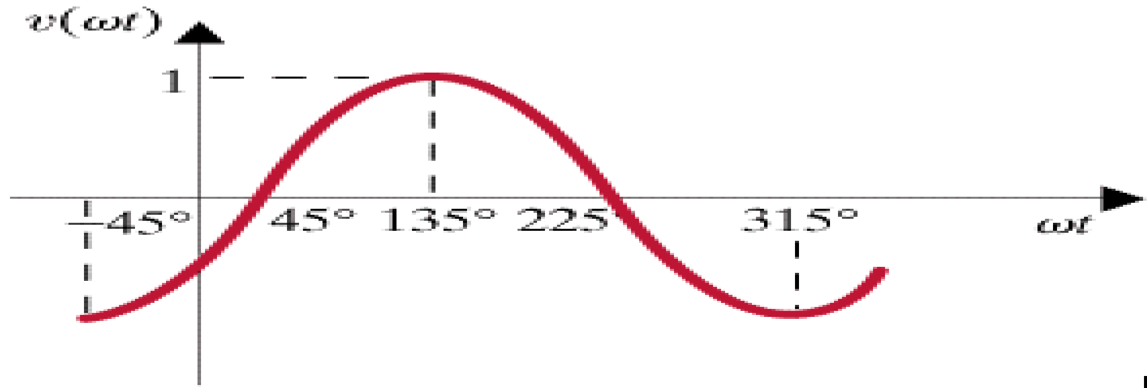
$\cos(\omega t + 45 - 360)$



$-\cos(\omega t + 45°)$

$\cos(\omega t + 45 \pm 180)$

Leads by 225 or lags by 135



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GEAUX

LEARNING EXAMPLE

$$v_1(t) = 12\sin(1000t + 60°),\ v_2(t) = -6\cos(1000t + 30°)$$

FIND FREQUENCY AND PHASE ANGLE BETWEEN VOLTAGES

Frequency in radians per second is the factor of the time variable $\omega = 1000\sec^{-1}$

$$f(Hz) = \frac{\omega}{2\pi} = 159.2Hz$$

To find phase angle we must express both sinusoids using the same trigonometric function; either sine or cosine with positive amplitude

take care of minus sign with $\cos(\alpha) = -\cos(\alpha \pm 180°)$

$$-6\cos(1000t + 30°) = 6\cos(1000t + 30° + 180°)$$

Change sine into cosine with $\cos(\alpha) = \sin(\alpha + 90°)$

$$6\cos(1000t + 210°) = 6\sin(1000t + 210° + 90°)$$

We like to have the phase shifts less than 180 in absolute value

$$6\sin(1000t + 300°) = 6\sin(1000t - 60°)$$

$$v_1(t) = 12\sin(1000t + 60°)$$
$$v_2(t) = 6\sin(1000t - 60°)$$

$$(1000t + 60°) - (1000t - 60°) = 120°$$

v_1 leads v_2 by 120°

$$(1000t - 60°) - (1000t + 60°) = -120°$$

v_2 lags v_1 by 120°

GEAUX

LEARNING EXTENSION

$$i_1(t) = 2\sin(377t + 45°)$$

$$i_2(t) = 0.5\cos(377t + 10°)$$

$$i_3(t) = -0.25\sin(377t + 60°)$$

i_1 leads i_2 by_____?

i_1 leads i_3 by_____?

$$\cos\alpha = \sin(\alpha + 90°)$$

$$0.5\cos(377t + 10°) = 0.5\sin(377t + 10° + 90°)$$

$$(377t + 45°) - (377 + 100°) = -55°$$

i_1 leads i_2 by $-55°$

$$\sin\alpha = -\sin(\alpha \pm 180°)$$

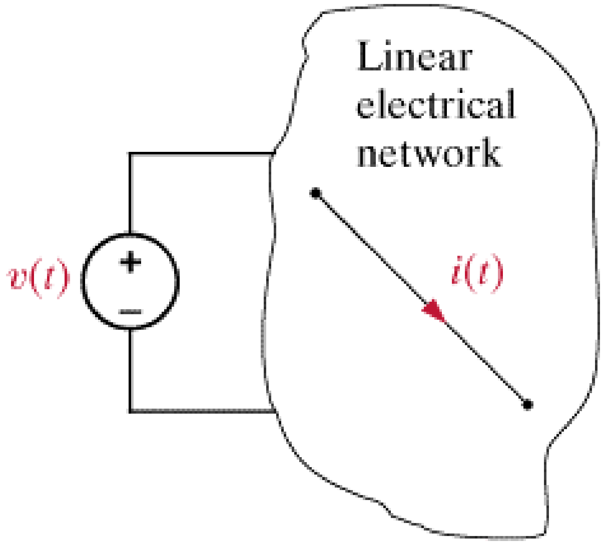
$$-0.25\sin(377t + 60°) = 0.25\sin(377t + 60° - 180°)$$

$$(377t + 45°) - (377t - 120°) = 165°$$

i_1 leads i_3 by $165°$

GEAUX

SINUSOIDAL AND COMPLEX FORCING FUNCTIONS



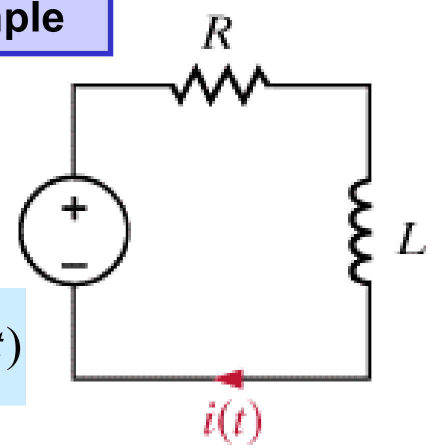
If the independent sources are sinusoids of the same frequency then for any variable in the linear circuit the steady state response will be sinusoidal and of the same frequency

$$v(t) = A\sin(\omega t + \theta) \Rightarrow i_{SS}(t) = B\sin(\omega t + \phi)$$

To determine the steady state solution we only need to determine the parameters

B, ϕ

Learning Example



$v(t) = V_M \cos \omega t$

KVL: $L\dfrac{di}{dt}(t) + Ri(t) = v(t)$

In steady state $i(t) = A\cos(\omega t + \phi)$, or

$$i(t) = A_1 \cos \omega t + A_2 \sin \omega t \qquad */R$$

$$\frac{di}{dt}(t) = -A_1\omega \sin \omega t + A_2 \omega \cos \omega t \qquad */L$$

$$(-L\omega A_1 + RA_2)\sin \omega t + (L\omega A_2 + RA_1)\cos \omega t =$$
$$= V_M \cos \omega t$$

$$-L\omega A_1 + RA_2 = 0$$
$$L\omega A_2 + RA_1 = V_M$$

algebraic problem

$$A_1 = \frac{RV_M}{R^2 + (\omega L)^2}, \quad A_2 = \frac{\omega L V_M}{R^2 + (\omega L)^2}$$

Determining the steady state solution can be accomplished with only algebraic tools!

FURTHER ANALYSIS OF THE SOLUTION

The solution is $i(t) = A_1 \cos\omega t + A_2 \sin\omega t$

The applied voltage is $v(t) = V_M \cos\omega t$

For comparison purposes one can write $i(t) = A\cos(\omega t + \phi)$

$$A_1 = A\cos\phi, \quad A_2 = -A\sin\phi$$

$$A = \sqrt{A_1^2 + A_2^2}, \ \tan\phi = -\frac{A_2}{A_1}$$

$$A_1 = \frac{RV_M}{R^2 + (\omega L)^2}, \quad A_2 = \frac{\omega L V_M}{R^2 + (\omega L)^2}$$

$$A = \frac{V_M}{\sqrt{R^2 + (\omega L)^2}}, \quad \phi = \tan^{-1}\frac{\omega L}{R}$$

$$i(t) = \frac{V_M}{\sqrt{R^2 + (\omega L)^2}}\cos(\omega t - \tan^{-1}\frac{\omega L}{R})$$

For $L \neq 0$ the current ALWAYS lags the voltage

If $R = 0$ (pure inductor) the current lags the voltage by 90°

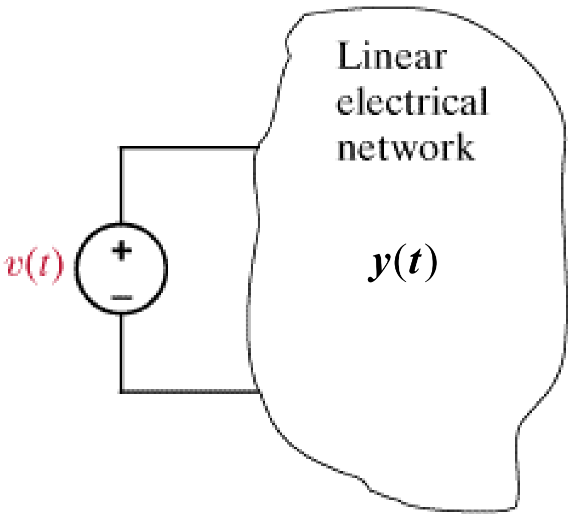
GEAUX

SOLVING A SIMPLE ONE LOOP CIRCUIT CAN BE VERY LABORIOUS IF ONE USES SINUSOIDAL EXCITATIONS

TO MAKE ANALYSIS SIMPLER ONE RELATES SINUSOIDAL SIGNALS TO COMPLEX NUMBERS. THE ANALYSIS OF STEADY STATE WILL BE CONVERTED TO SOLVING SYSTEMS OF ALGEBRAIC EQUATIONS ...

... WITH COMPLEX VARIABLES

ESSENTIAL IDENTITY: $e^{j\theta} = \cos\theta + j\sin\theta$ (Euler identity)



$$v(t) = V_M \cos\omega t \rightarrow y(t) = A\cos(\omega t + \phi)$$

$$v(t) = V_M \sin\omega t \rightarrow y(t) = A\sin(\omega t + \phi)$$

$* / j$ (and add)

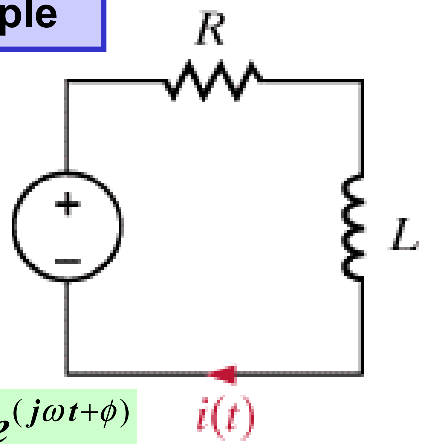
$$V_M e^{j\omega t} \rightarrow A e^{j(\omega t + \phi)} = A e^{j\theta} e^{j\omega t}$$

If everybody knows the frequency of the sinusoid then one can skip the term *exp(jwt)*

$$V_M \rightarrow A e^{j\theta}$$

GEAUX

Learning Example



$$v(t) = V_M e^{j\omega t}$$

Assume $i(t) = I_M e^{(j\omega t + \phi)}$

$$\text{KVL}: \; L\frac{di}{dt}(t) + Ri(t) = v(t)$$

$$\frac{di}{dt}(t) = j\omega I_M e^{(j\omega t+\phi)}$$

$$L\frac{di}{dt}(t) + Ri(t) = j\omega L I_M e^{(j\omega t+\phi)} + R I_M e^{(j\omega t+\phi)}$$

$$= (j\omega L + R) I_M e^{(j\omega t+\phi)}$$

$$= (j\omega L + R) I_M e^{j\phi} e^{j\omega t}$$

$$(j\omega L + R) I_M e^{j\phi} e^{j\omega t} = V_M e^{j\omega t}$$

$$I_M e^{j\phi} = \frac{V_M}{j\omega L + R} \quad */ \frac{R - j\omega L}{R - j\omega L}$$

$$I_M e^{j\phi} = \frac{V_M (R - j\omega L)}{R^2 + (\omega L)^2}$$

$$R - j\omega L = \sqrt{R^2 + (\omega L)^2}\, e^{-\tan^{-1}\frac{\omega L}{R}}$$

$$I_M e^{j\phi} = \frac{V_M}{\sqrt{R^2 + (\omega L)^2}} e^{-\tan^{-1}\frac{\omega L}{R}}$$

$$I_M = \frac{V_M}{\sqrt{R^2 + (\omega L)^2}}, \quad \phi = -\tan^{-1}\frac{\omega L}{R}$$

$$v(t) = V_M \cos \omega t = \mathrm{Re}\{V_M e^{j\omega t}\}$$

$$\Rightarrow i(t) = \mathrm{Re}\{I_M e^{(j\omega t - \phi)}\} = I_M \cos(\omega t - \phi)$$

$C \leftrightarrow P$

$$x + jy = re^{j\theta}$$

$$r = \sqrt{x^2 + y^2}, \quad \theta = \tan^{-1}\frac{x}{y}$$

$$x = r\cos\theta, \quad y = r\sin\theta$$

PHASORS

ESSENTIAL CONDITION
ALL INDEPENDENT SOURCES ARE SINUSOIDS OF THE SAME FREQUENCY

BECAUSE OF SOURCE SUPERPOSITION ONE CAN CONSIDER A SINGLE SOURCE

$$u(t) = U_M \cos(\omega t + \theta)$$

THE STEADY STATE RESPONSE OF ANY CIRCUIT VARIABLE WILL BE OF THE FORM

$$y(t) = Y_M \cos(\omega t + \phi)$$

SHORTCUT 1

$$u(t) = U_M e^{j(\omega t + \theta)} \Rightarrow y(t) = Y_M e^{j(\omega t + \phi)}$$

$$\mathrm{Re}\{U_M e^{j(\omega t + \theta)}\} \Rightarrow \mathrm{Re}\{Y_M e^{j(\omega t + \phi)}\}$$

NEW IDEA: $U_M e^{j(\omega t + \theta)} = U_M e^{j\theta} e^{j\omega t}$ $\quad u = U_M e^{j\theta} \Rightarrow y = Y_M e^{j\phi}$

SHORTCUT IN NOTATION

INSTEAD OF WRITING $u = U_M e^{j\theta}$ WE WRITE $u = U_M \angle \theta$

... AND WE ACCEPT ANGLES IN DEGREES

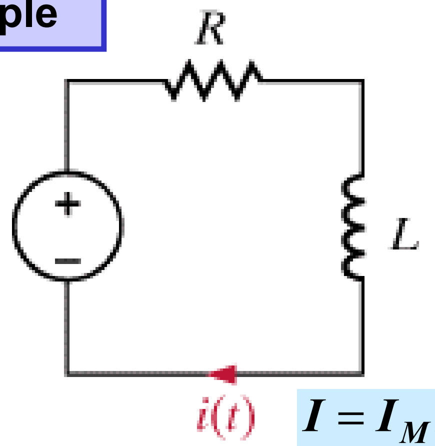
$U_M \angle \theta$ IS THE PHASOR REPRESENTATION FOR $U_M \cos(\omega t + \theta)$

$$u(t) = U_M \cos(\omega t + \theta) \rightarrow U = U_M \angle \theta \Rightarrow Y = Y_M \angle \phi \rightarrow y(t) = \mathrm{Re}\{Y_M \cos(\omega t + \phi)\}$$

SHORTCUT 2: DEVELOP EFFICIENT TOOLS TO DETERMINE THE PHASOR OF THE RESPONSE GIVEN THE INPUT PHASOR(S)

Learning Example

$v(t) = V_M \cos \omega t$



$$V = V_M \angle 0$$
$$v = Ve^{j\omega t}$$

$$I = I_M \angle \phi$$
$$i = Ie^{j\omega t}$$

$$L\frac{di}{dt}(t) + Ri(t) = v$$
$$L(j\omega Ie^{j\omega t}) + RIe^{j\omega t} = Ve^{j\omega t}$$

In terms of phasors one has

$$j\omega LI + RI = V$$
$$I = \frac{V}{R + j\omega L}$$

The phasor can be obtained using only complex algebra

We will develop a phasor representation for the circuit that will eliminate the need of writing the differential equation

Learning Extensions

It is essential to be able to move from sinusoids to phasor representation

$$A\cos(\omega t \pm \theta) \leftrightarrow A\angle \pm \theta$$
$$A\sin(\omega t \pm \theta) \leftrightarrow A\angle \pm \theta - 90°$$

$$v(t) = 12\cos(377t - 425°) \leftrightarrow \quad 12\angle - 425°$$
$$y(t) = 18\sin(2513t + 4.2°) \leftrightarrow \quad 18\angle - 85.8°$$

Given $f = 400Hz$

$$V_1 = 10\angle 20° \leftrightarrow \quad v_1(t) = 10\cos(800\pi t + 20°)$$
$$V_2 = 12\angle - 60° \leftrightarrow v_2(t) = 12\cos(800\pi t - 60°)$$

Phasors can be combined using the rules of complex algebra

$$(V_1\angle\theta_1)(V_2\angle\theta_2) = V_1V_2\angle(\theta_1 + \theta_2)$$
$$\frac{V_1\angle\theta_1}{V_2\angle\theta_2} = \frac{V_1}{V_2}\angle(\theta_1 - \theta_2)$$

PHASOR RELATIONSHIPS FOR CIRCUIT ELEMENTS

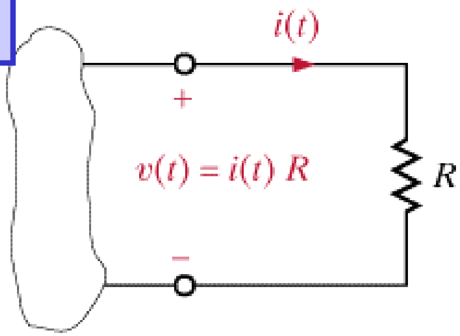
RESISTORS

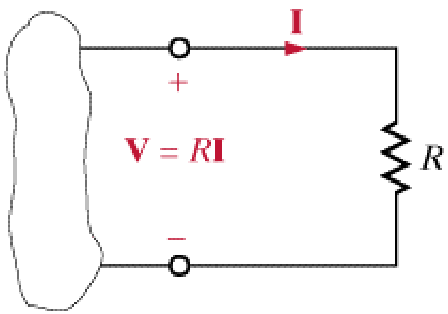
$$v(t) = Ri(t)$$

$$V_M e^{(j\omega t+\theta)} = RI_M e^{(j\omega t+\theta)}$$

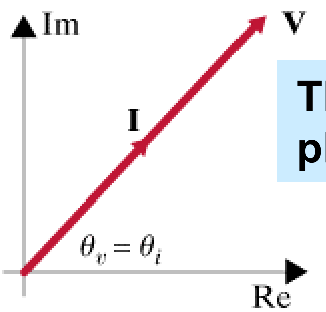
$$V_M e^{j\theta} = RI_M e^{j\theta}$$

$V = RI$ **Phasor representation for a resistor**

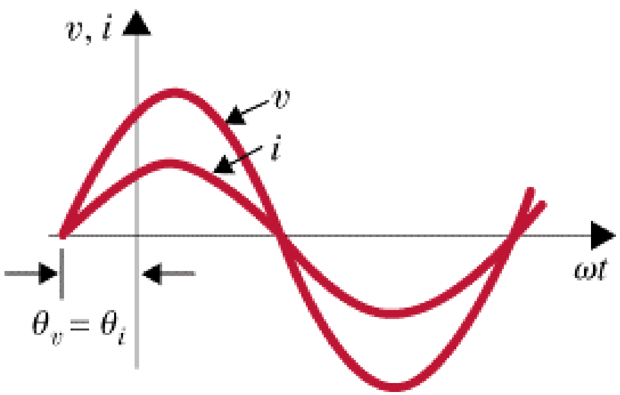




Phasors are complex numbers. The resistor model has a geometric interpretation



The voltage and current phasors are colineal



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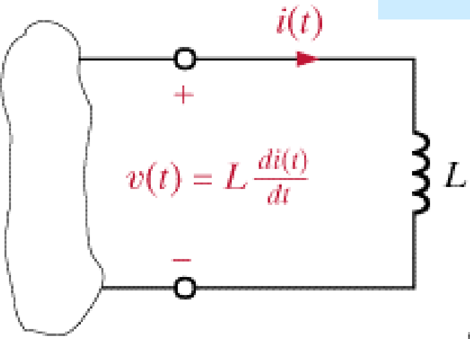
In terms of the sinusoidal signals this geometric representation implies that the two sinusoids are "in phase"

GEAUX

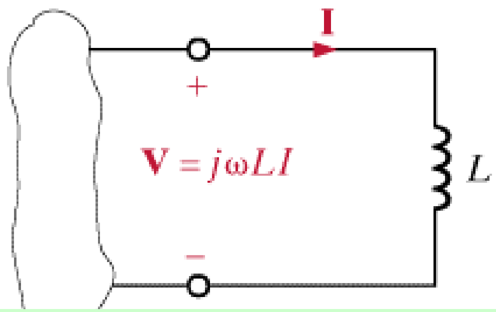
INDUCTORS



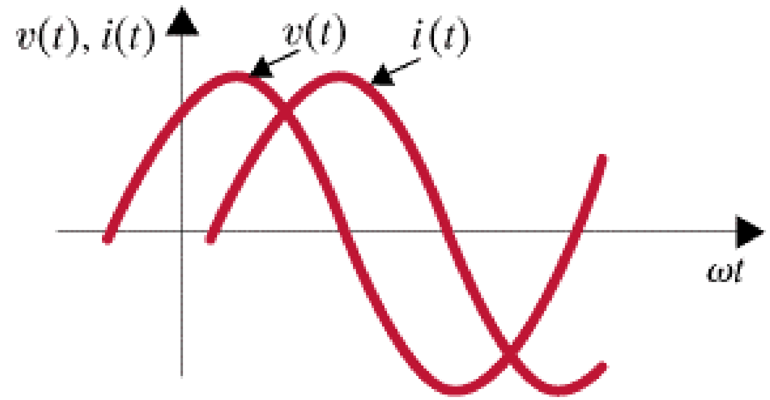
$$V_M e^{(j\omega t+\theta)} = L\frac{d}{dt}(I_M e^{(j\omega t+\phi)})$$
$$= j\omega L I_M e^{(j\omega t+\phi)}$$

$$V_M e^{j\theta} = j\omega L I_M e^{j\phi}$$

$$V = j\omega L I$$



Relationship between sinusoids



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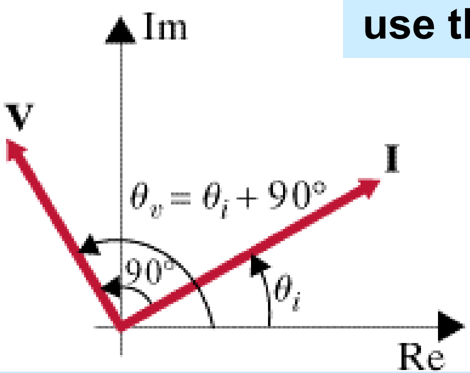
The relationship between phasors is algebraic

For the geometric view use the result

$$j = 1\angle 90° = e^{j90°}$$

$$V = \omega L I \angle 90°$$



The voltage leads the current by 90 deg
The current lags the voltage by 90 deg

Learning Example

$L = 20mH, v(t) = 12\cos(377t + 20°)$. Find $i(t)$

$$\omega = 377$$
$$V = 12\angle 20°$$
$$I = \frac{V}{j\omega L}$$

$$I = \frac{12\angle 20°}{\omega L\angle 90°}(A)$$

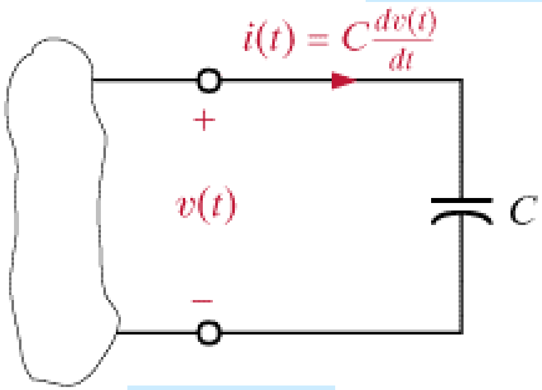
$$I = \frac{12}{377\times 20\times 10^{-3}}\angle -70°(A)$$

$$i(t) = \frac{12}{377\times 20\times 10^{-3}}\cos(377t - 70°)$$

GEAUX

CAPACITORS

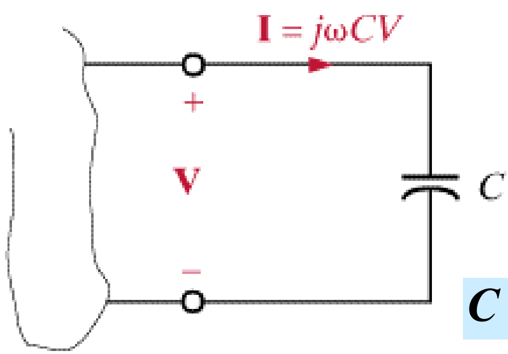
$$I_M e^{(j\omega t+\phi)} = C\frac{d}{dt}(V_M e^{(j\omega t+\theta)})$$



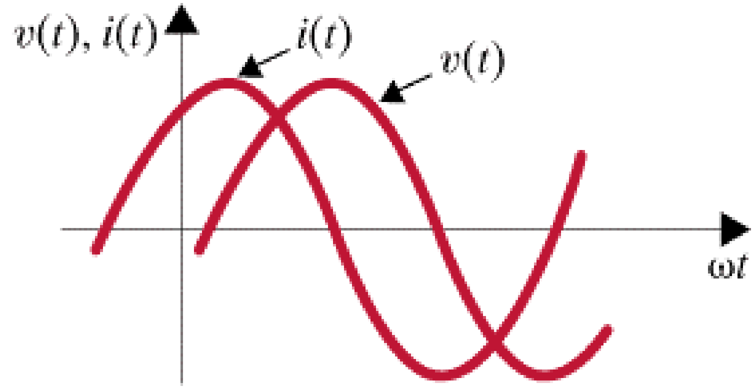
$$I_M e^{j\phi} = j\omega C e^{j\theta}$$

$$I = j\omega CV$$

$$I = \omega CV\angle 90°$$



Relationship between sinusoids



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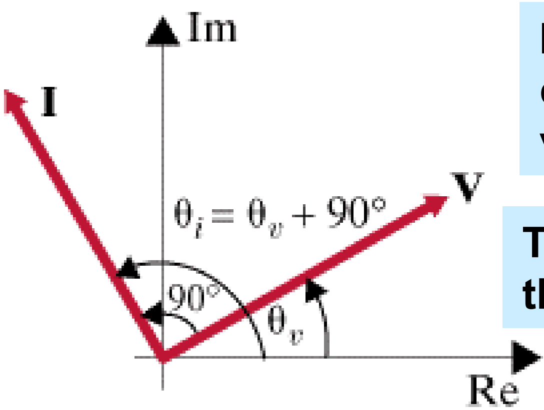
The relationship between phasors is algebraic



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In a capacitor the current leads the voltage by 90 deg

The voltage lags the current by 90 deg

Learning Example

$C = 100\mu F, v(t) = 100\cos(314t + 15°)$. Find $i(t)$

$$\omega = 314$$

$$V = 100\angle 15°$$

$$I = j\omega CV$$

$$I = \omega C \times 1\angle 90° \times 100\angle 15°$$

$$I = 314 \times 100 \times 10^{-6} \times 100\angle 105°(A)$$

$$i(t) = 3.14\cos(314t + 105°)(A)$$

GEAUX

LEARNING EXTENSIONS

$L = 0.05H,\ I = 4\angle -30°(A),\ f = 60Hz$

Find the voltage across the inductor

$\omega = 2\pi f = 120\pi$

$V = j\omega LI$

$V = 120\pi \times 0.05 \times 1\angle 90° \times 4\angle -30°$

$V = 24\pi\angle 60°$

$v(t) = 24\pi\cos(120\pi + 60°)$

Now an example with capacitors

$C = 150\mu F,\ I = 3.6\angle -145°,\ f = 60Hz$

Find the voltage across the inductor

$\omega = 2\pi f = 120\pi$

$I = j\omega CV \Rightarrow V = \dfrac{I}{j\omega C}$

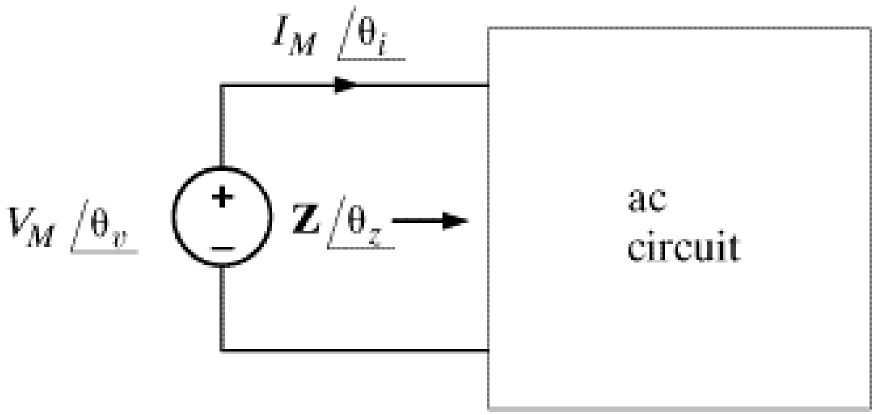
$$V = \frac{3.6\angle -145°}{120\pi \times 150 \times 10^{-6} \times 1\angle 90°}$$

$$V = \frac{200}{\pi}\angle -235°$$

$$v(t) = \frac{200}{\pi}\cos(120\pi t - 235°)$$

IMPEDANCE AND ADMITTANCE

For each of the passive components the relationship between the voltage phasor and the current phasor is algebraic. We now generalize for an arbitrary 2-terminal element



$$Z(\omega) = R(\omega) + jX(\omega)$$

$R(\omega)$=Resistive component

$X(\omega)$=Reactive component

$$|Z| = \sqrt{R^2 + X^2}$$

$$\theta_z = \tan^{-1}\frac{X}{R}$$

(INPUT) IMPEDANCE

$$Z = \frac{V}{I} = \frac{V_M\angle\theta_v}{I_M\angle\theta_i} = \frac{V_M}{I_M}\angle(\theta_v - \theta_i) = |Z|\angle\theta_z$$

(DRIVING POINT IMPEDANCE)

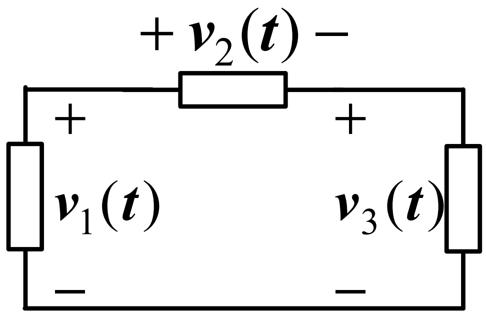
The units of impedance are OHMS

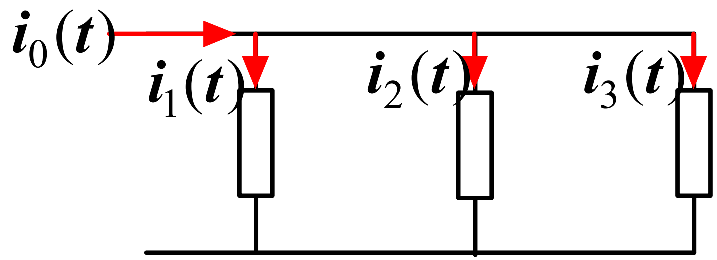
Element	Phasor Eq.	Impedance
R	$V = RI$	$Z = R$
L	$V = j\omega LI$	$Z = j\omega L$
C	$V = \frac{1}{j\omega C} I$	$Z = \frac{1}{j\omega C}$

Impedance is NOT a phasor but a complex number that can be written in polar or Cartesian form. In general its value depends on the frequency

GEAUX

KVL AND KCL HOLD FOR PHASOR REPRESENTATIONS





KVL: $v_1(t)+v_2(t)+v_3(t)=0$

KCL: $-i_0(t)+i_1(t)+i_2(t)+i_3(t)=0$

$$v_i(t)=V_{Mi}e^{j(\omega t+\theta_i)},\ i=1,2,3$$

$$i_k(t)=I_{Mk}e^{j(\omega t+\phi_k)},\ k=0,1,2,3$$

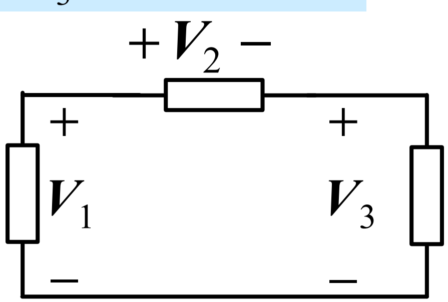
KVL: $(V_{M1}e^{j\theta_1}+V_{M2}e^{j\theta_2}+V_{M3}e^{j\theta_3})e^{j\omega t}=0$

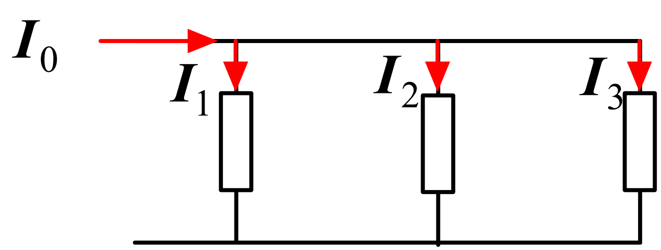
In a similar way, one shows ...

$$V_{M1}\angle\theta_1+V_{M2}\angle\theta_2+V_{M3}\angle\theta_3=0$$

$V_1+V_2+V_3=0$ Phasors!

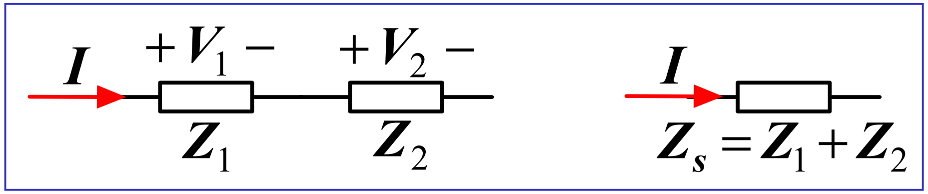
$$-I_0+I_1+I_2+I_3=0$$



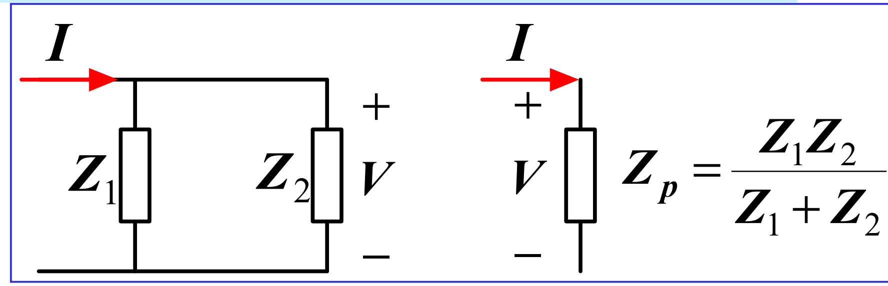


The components will be represented by their impedances and the relationships will be entirely algebraic!!

SPECIAL APPLICATION:
IMPEDANCES CAN BE COMBINED USING THE SAME RULES DEVELOPED FOR RESISTORS



$$Z_s = \sum_k Z_k$$

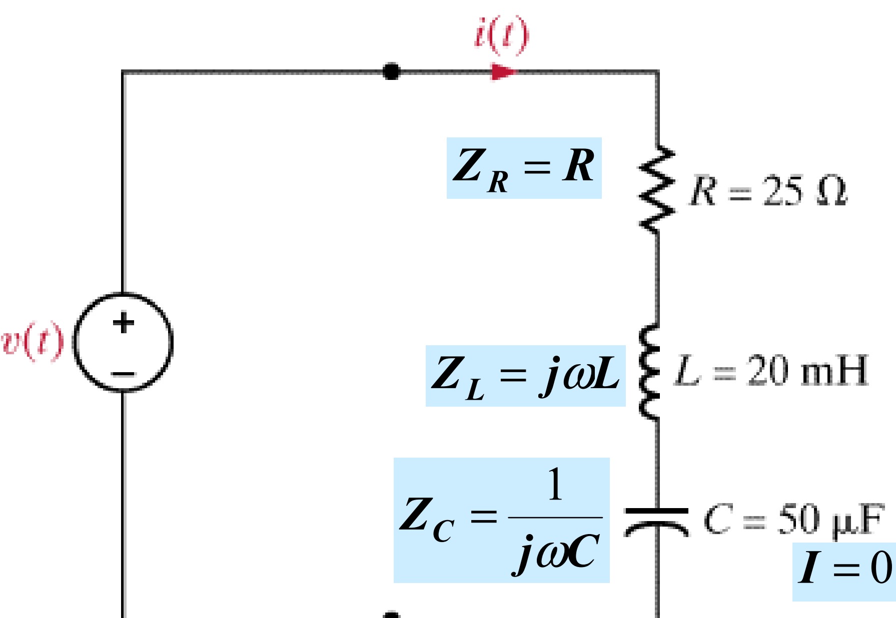


$$\frac{1}{Z_p} = \sum_k \frac{1}{Z_k}$$

LEARNING EXAMPLE

$f = 60Hz, v(t) = 50\cos(\omega t + 30°)$

Compute equivalent impedance and current



$$\omega = 120\pi,\ V = 50\angle 30°,\ Z_R = 25\Omega$$

$$Z_L = j120\pi \times 20 \times 10^{-3}\Omega,\ Z_C = \frac{1}{j120\pi \times 50 \times 10^{-6}}$$

$$Z_L = j7.54\Omega,\ \ Z_C = -j53.05\Omega$$

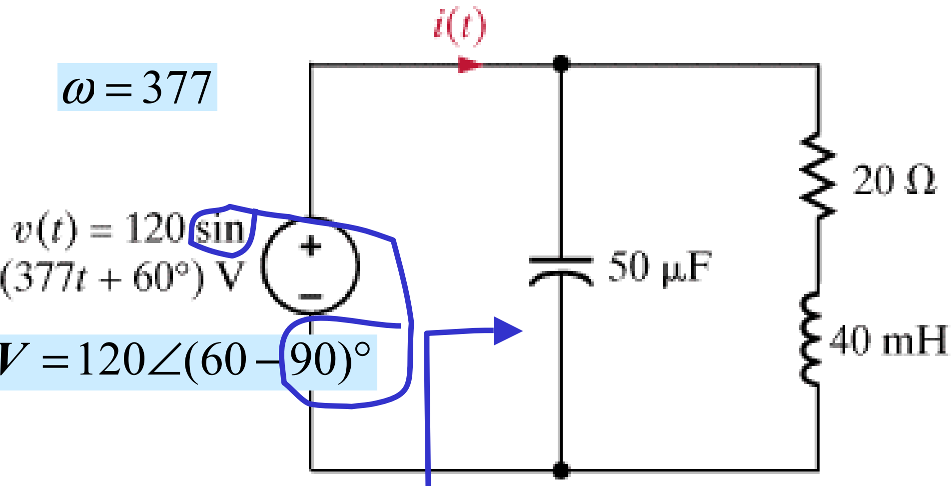
$$Z_s = Z_R + Z_L + Z_C = 25 - j45.51\Omega$$

$$I = \frac{V}{Z_s} = \frac{50\angle 30°}{25 - j45.51}(A) = \frac{50\angle 30°}{51.93\angle -61.22°}(A)$$

$$I = 0.96\angle 91.22°(A) \Rightarrow i(t) = 0.96\cos(120\pi t + 91.22°)(A)$$

LEARNING EXTENSION FIND $i(t)$

$\omega = 377$



$V = 120\angle(60-90)°$

$Z_R = 20\Omega$

$Z_L = j377\times 40\times 10^{-3} = j15.08\Omega$

$$Z_C = \frac{j}{377\times 50\times 10^{-6}} = -j53.05$$

$Z_{eq} = Z_C \parallel (Z_R + Z_L)$

$Z_{eq} = 30.5616 + j4.9714 = 30.963\angle 9.239°$

$$I = \frac{V}{Z_{eq}} = \frac{120\angle -30°}{30.963\angle 9.239°} = 3.876\angle -39.924°(A)$$

GEAUX

(COMPLEX) ADMITTANCE

$$Y = \frac{1}{Z} = G + jB \text{ (Siemens)}$$

G = conductance

B = Suceptance

$$\frac{1}{Z} = \frac{1}{R + jX} \times \frac{R - jX}{R - jX} = \frac{R - jX}{R^2 + X^2}$$

$$G = \frac{R}{R^2 + X^2}$$

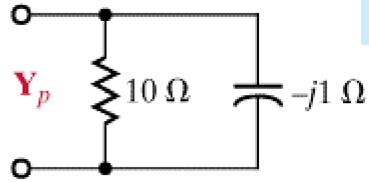
$$B = \frac{-X}{R^2 + X^2}$$

Element	Phasor Eq.	Impedance	Admittance
R	$V = RI$	$Z = R$	$Y = \frac{1}{R} = G$
L	$V = j\omega LI$	$Z = j\omega L$	$Y = \frac{1}{j\omega L}$
C	$V = \frac{1}{j\omega C} I$	$Z = \frac{1}{j\omega C}$	$Y = j\omega C$

Parallel Combination of Admittances

$$Y_p = \sum_k Y_k$$

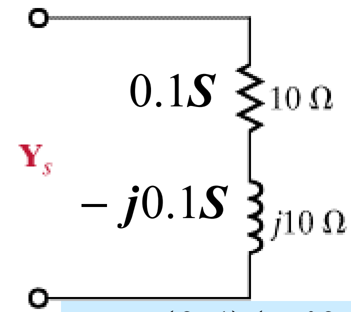
$$Y_R = 0.1S \qquad Y_C = \frac{1}{-j1} = j1(S)$$



$$Y_p = 0.1 + j1(S)$$

Series Combination of Admittances

$$\frac{1}{Y_s} = \sum_k \frac{1}{Y_k}$$



$0.1S$

$-j0.1S$

$$\frac{1}{Y_s} = \frac{1}{0.1} + \frac{1}{-j0.1} = 10 + j10$$

$$Y_s = \frac{(0.1)(-j0.1)}{0.1 - j0.1} \times \frac{0.1 + j0.1}{0.1 + j0.1}$$

$$Y_s = \frac{1}{10 + j10} = \frac{10 - j10}{200}$$

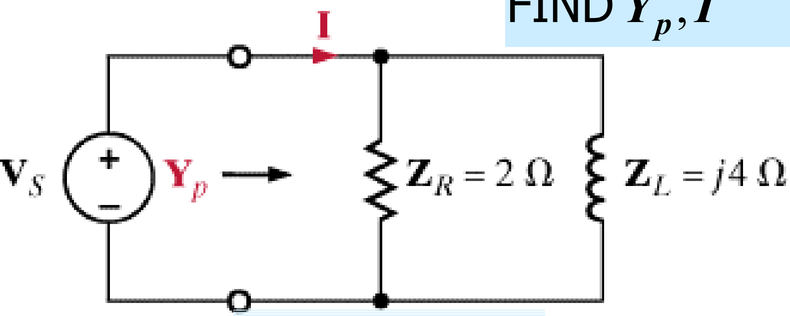
$$Y_s = 0.05 - j0.05S$$

GEAUX

LEARNING EXAMPLE

$V_S = 60\angle 45°(V)$

FIND Y_p, I



$$Y_p = Y_R + Y_L$$
$$= 0.5 - j0.25$$

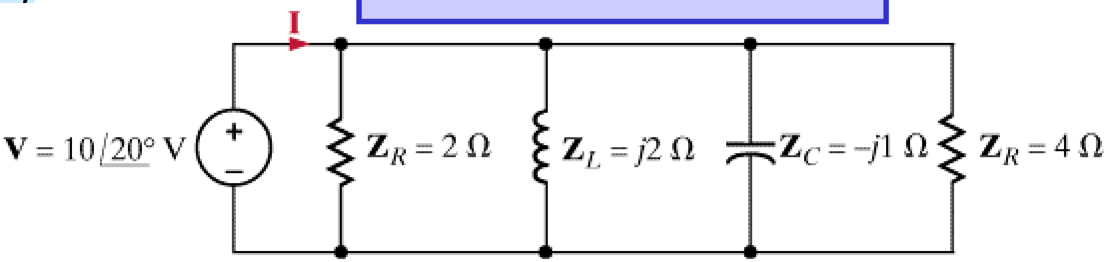
$$Z_p = \frac{2 \times j4}{2 + j4} \quad Y_p = \frac{2 + j4}{j8} = 0.5 - j0.25(S)$$

$$I = Y_p V = (0.5 - j0.25) \times 60\angle 45°(A)$$

$$I = 0.559\angle -26.565° \times 60\angle 45°(A)$$

$$I = 33.54\angle 18.435°(A)$$

LEARNING EXTENSION



$$Y_p = 0.5 - j0.5 + j1 + 0.25 = 0.75 + j0.5(S)$$

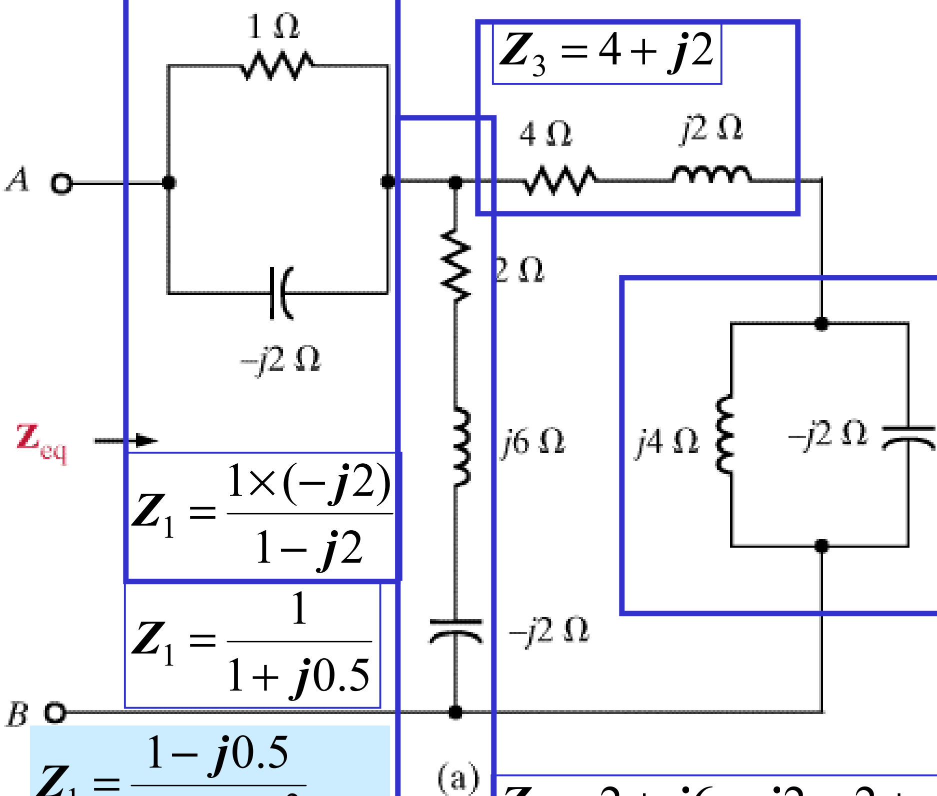
$$Y_p = 0.9014\angle 33.69°(S)$$

$$I = Y_p V = 0.9014\angle 33.69° \times 10\angle 20°$$
$$I = 9.014\angle 53.79°(A)$$

GEAUX

LEARNING EXAMPLE

SERIES-PARALLEL REDUCTIONS



$Z_3 = 4 + j2$

$Z_1 = \dfrac{1\times(-j2)}{1-j2}$

$Z_1 = \dfrac{1}{1+j0.5}$

$Z_1 = \dfrac{1-j0.5}{1+(0.5)^2}$

$Z_1 = 0.8 - j0.4(\Omega)$

$Z_2 = 2 + j6 - j2 = 2 + j4$

$Y_4 = -j0.25 + j0.5 = j0.25$

$Z_4 = 1/Y_4 = -j4$

$Z_4 = \dfrac{j4\times(-j2)}{j4-j2} = \dfrac{8}{j2}$

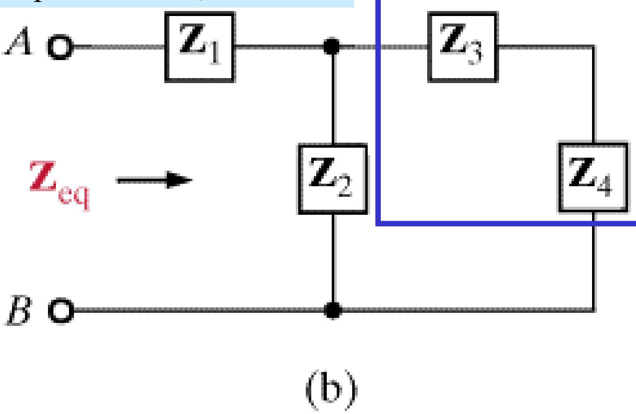
$Y_2 = \dfrac{1}{2+j4} = \dfrac{2-j4}{(2)^2+(4)^2}$

$Y_{34} = \dfrac{1}{4-j2} = \dfrac{4+j2}{20}$

$Y_2 = 0.1 - j0.2(S)$

$Y_{34} = 0.2 + j0.1$

$Y_{234} = 0.3 - j0.1(S)$



$Z_{34} = 4 - j2$

$Z_{234} = \dfrac{1}{Y_{234}} = \dfrac{1}{0.3-j0.1} = \dfrac{0.3+j0.1}{0.1}$

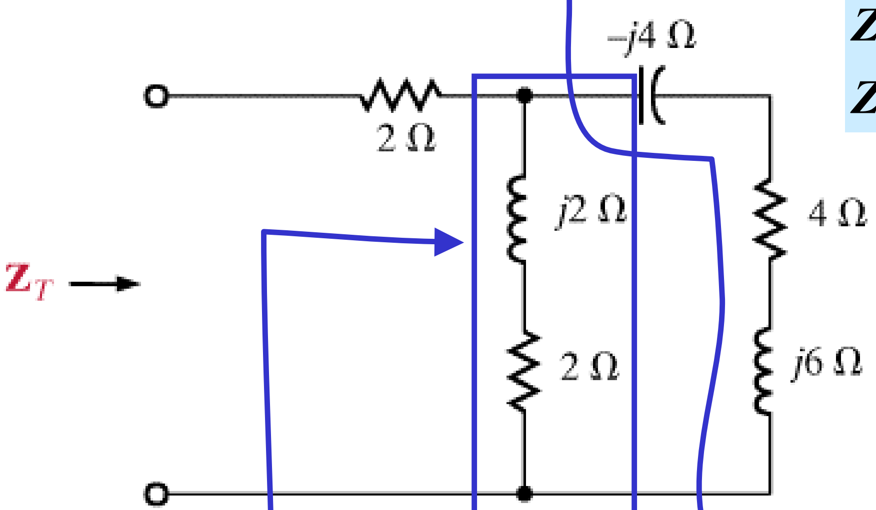
$Z_{234} = \dfrac{Z_2 Z_{34}}{Z_2 + Z_{34}}$ $= 3 + j1$

$Z_{eq} = Z_1 + Z_{234} = 3.8 + j0.6\Omega = 3.847\angle 8.973°$

GEAUX

LEARNING EXTENSION

FIND THE IMPEDANCE Z_T



$$Z_1 = 4 + j6 - j4$$
$$Z_1 = 4 + j2$$

$$(R \to P) Z_1 = 4.472\angle 26.565°$$
$$Y_1 = 0.224\angle -26.565°$$
$$(P \to R) Y_1 = 0.200 - j0.100$$

$$Y_{12} = Y_1 + Y_2$$
$$Z_{12} = \frac{1}{Y_{12}}$$

$$Z_2 = 2 + j2$$

$$(R \to P) Z_2 = 2.828\angle 45°$$
$$Y_2 = 0.354\angle -45°$$
$$(P \to R) Y_2 = 0.250 - j0.250$$

$$Y_{12} = Y_1 + Y_2 = 0.45 - j0.35$$
$$(R \to P) Y_{12} = 0.570\angle -37.875°$$
$$Z_{12} = 1.754\angle 37.875°$$
$$(P \to R) Z_{12} = 1.384 + j1.077$$

$$Z_T = 2 + (1.384 + j1077) = 3.383 + j1.077$$

$$Y_1 = \frac{1}{4 + j2} = \frac{4 - j2}{(4)^2 + (2)^2}$$
$$Y_2 = \frac{1}{2 + j2} = \frac{2 - j2}{(2)^2 + (2)^2}$$
$$Z_{12} = \frac{1}{Y_{12}} = \frac{1}{0.45 - j0.35} = \frac{0.45 + j0.35}{0.325}$$

GEAUX

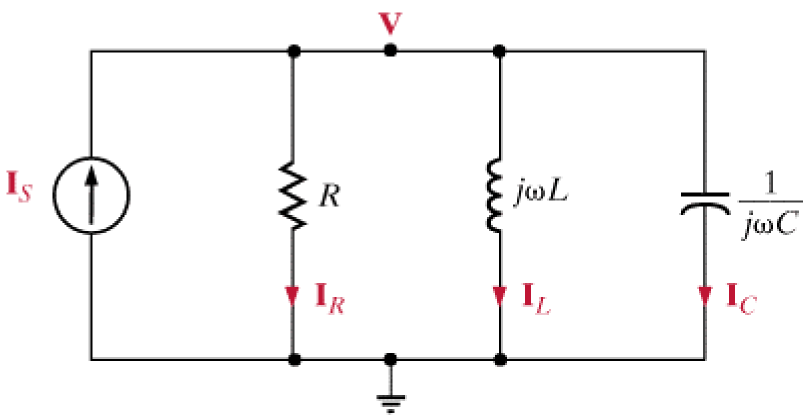
PHASOR DIAGRAMS

Display all relevant phasors on a common reference frame

Very useful to visualize phase relationships among variables. Especially if some variable, like the frequency, can change

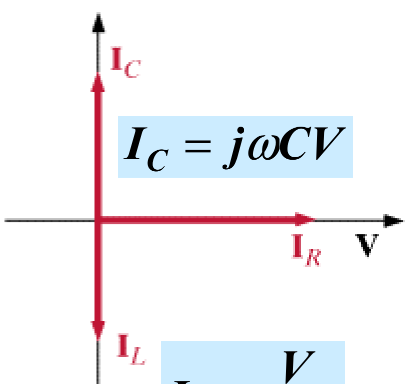
LEARNING EXAMPLE

SKETCH THE PHASOR DIAGRAM FOR THE CIRCUIT



Any one variable can be chosen as reference. For this case select the voltage V

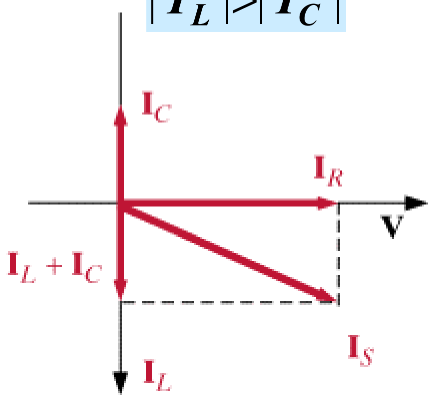
$$\text{KCL}: \; I_S = \frac{V}{R} + \frac{V}{j\omega L} + j\omega C V$$



$$I_C = j\omega C V$$

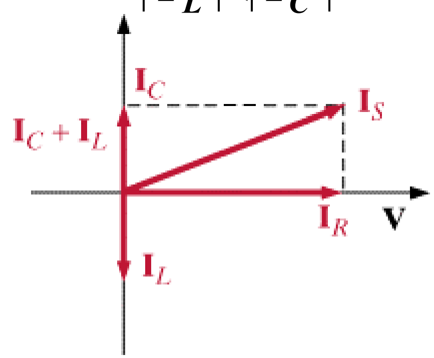
$$I_L = \frac{V}{j\omega l}$$

$$|I_L| > |I_C|$$



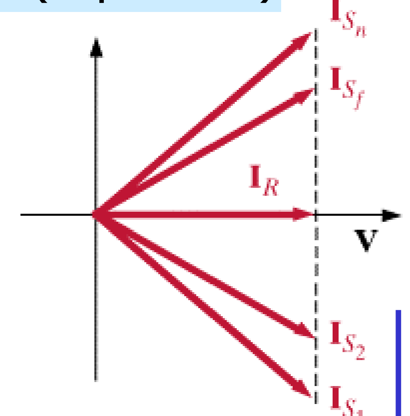
INDUCTIVE CASE

$$|I_L| < |I_C|$$



CAPACITIVE CASE

$\omega \uparrow$ (capacitive)



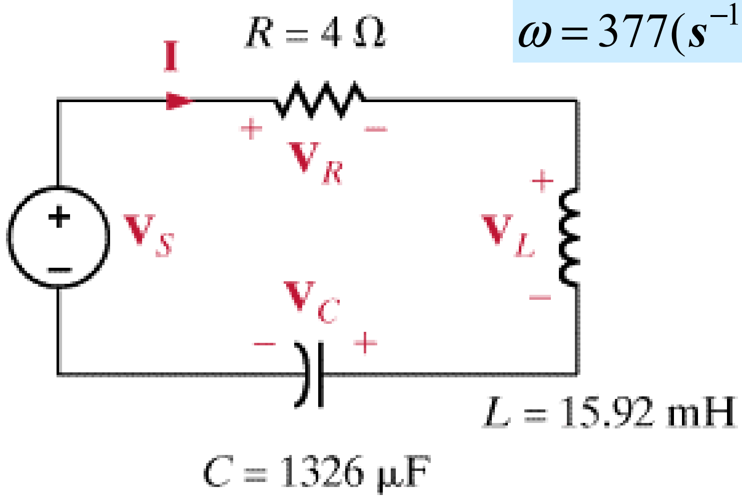
$\omega \uparrow$ (inductive)

GEAUX

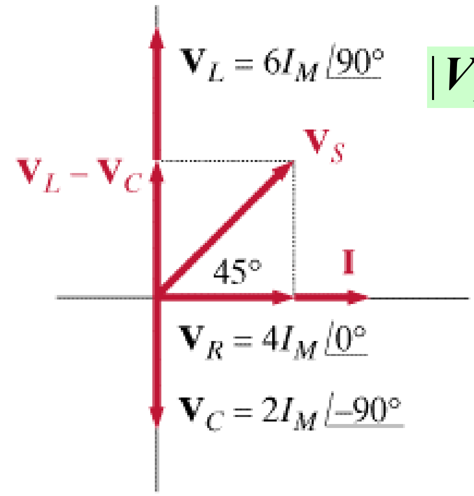
LEARNING EXAMPLE

DO THE PHASOR DIAGRAM FOR THE CIRCUIT

$\omega = 377 (s^{-1})$



2. PUT KNOWN NUMERICAL VALUES



$|V_L - V_C| = |V_R|$

$V_R = RI$

$V_L = j\omega L I$

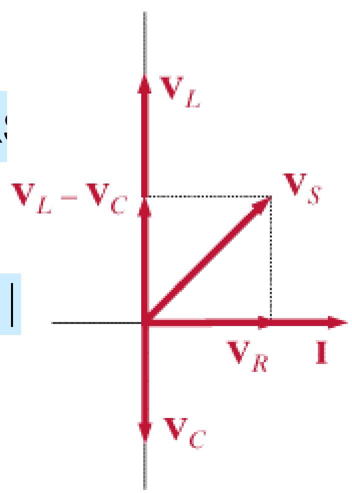
$V_C = \dfrac{1}{j\omega C} I$

$V_S = V_R + V_L + V_C$

It is convenient to select the current as reference

1. DRAW ALL THE PHASORS

$|V_L| > |V_C|$

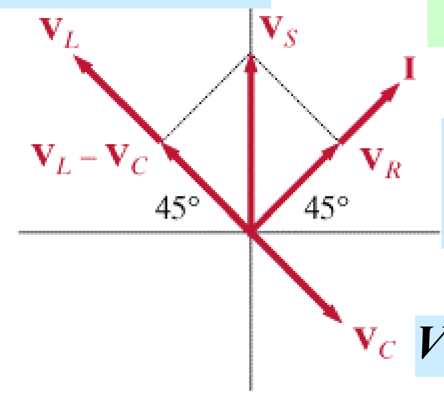


(b)

DIAGRAM WITH REFERENCE $V_S = 12\sqrt{2}\angle 90°$

$V_L = 18\angle 135° (V)$

Read values from diagram!



(d)

$\therefore I = 3\angle 45° (A)$

$V_R = 12\angle 45° (V)$

(Pythagoras)

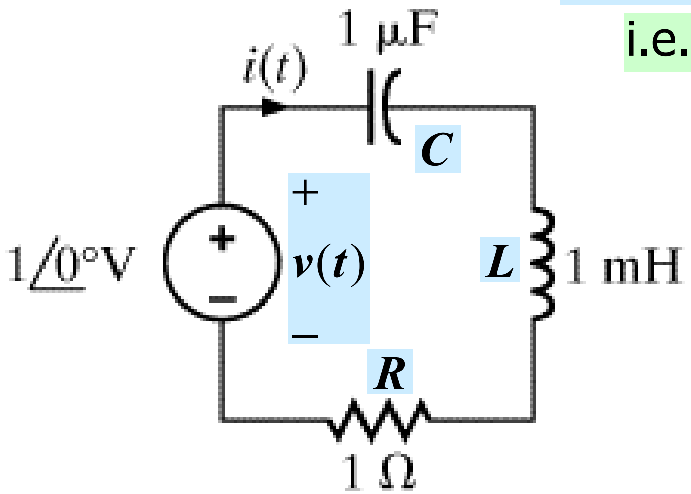
$V_C = 6\angle -45°$

LEARNING BY DOING

FIND THE FREQUENCY AT WHICH $v(t)$ AND $i(t)$ ARE IN PHASE

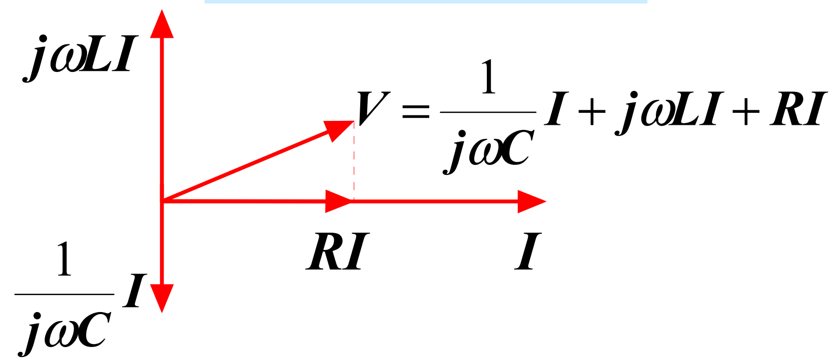
i.e., the phasors for $i(t), v(t)$ are co-lineal

$$V = \frac{1}{j\omega C} I + j\omega L I + RI$$



Notice that I was chosen as reference

PHASOR DIAGRAM



V and I are co-lineal iff $j\omega L + \frac{1}{j\omega C} = 0$ $\Rightarrow \omega^2 = \frac{1}{LC}$

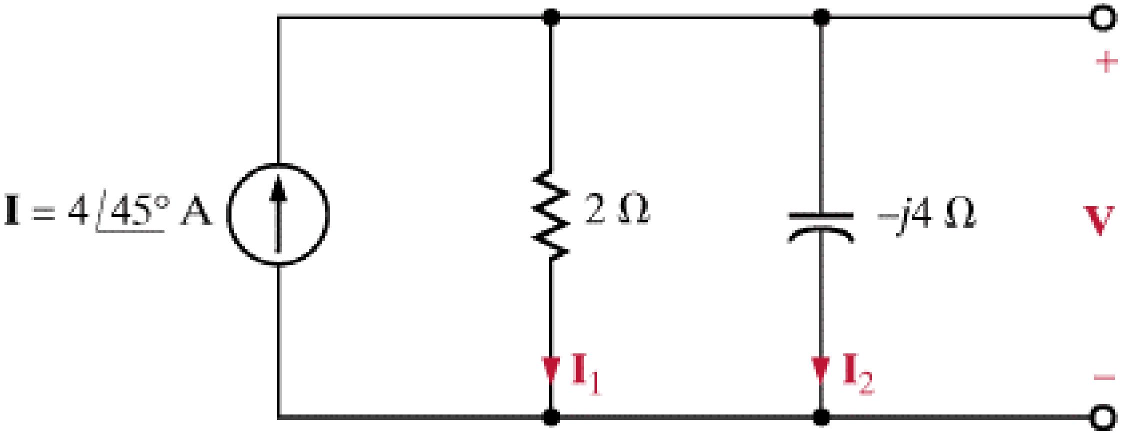
$$\omega^2 = \frac{1}{10^{-3} \times 10^{-6}} = 10^9 \Rightarrow \omega = 3.162 \times 10^4 (rad/s)$$

$$f = \frac{\omega}{2\pi} = 5.033 \times 10^3 \, Hz$$

GEAUX

LEARNING EXTENSION

Draw a phasor diagram illustrating all voltages and currents



$$I_1 = \frac{-j4}{2-j4} I = \frac{4\angle -90°}{4.472\angle -63.435°} 4\angle 45°$$

Current divider

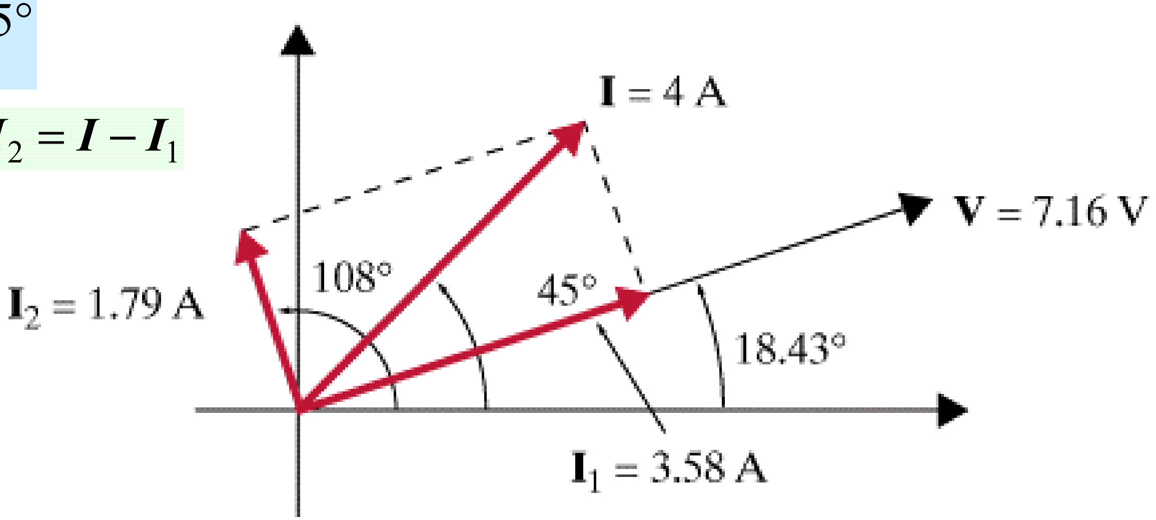
$$I_1 = 3.578\angle 18.435°(A)$$

$$I_2 = \frac{1}{2-j4} I = \frac{2\angle 0°}{4.472\angle -63.435°} 4\angle 45°$$

$I_2 = 1.789\angle 108.435°$ Simpler than $I_2 = I - I_1$

$$V = 2I_1 = 7.156\angle 18.435°(V)$$

DRAW PHASORS. ALL ARE KNOWN. NO NEED TO SELECT A REFERENCE



BASIC ANALYSIS USING KIRCHHOFF'S LAWS

PROBLEM SOLVING STRATEGY

For relatively simple circuits use

Ohm's law for AC analysis; i.e., $V = IZ$

The rules for combining Z and Y

KCL AND KVL

Current and voltage divider

For more complex circuits use

Node analysis

Loop analysis

Superposition

Source transformation

Thevenin's and Norton's theorems

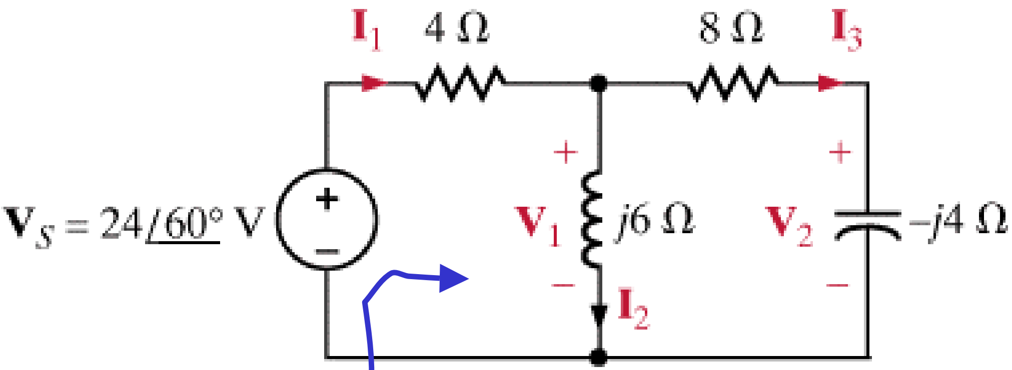
MATLAB

PSPICE

GEAUX

LEARNING EXAMPLE

COMPUTE ALL THE VOLTAGES AND CURRENTS



$$Z_{eq} = 4 + (j6 \,\|\, 8 - j4)$$

Compute I_1

Use current divider for I_2, I_3

Ohm's law for V_1, V_2

$$V_1 = 6\angle 90° I_2 \qquad V_2 = 4\angle -90° I_3$$

$$V_1 = 16.26\angle 78.42°(V)$$

$$V_2 = 7.28\angle 15°(V)$$

$$Z_{eq} = 4 + \frac{24 + j48}{8 + j2} = \frac{32 + j8 + 24 + j48}{8 + j2}$$

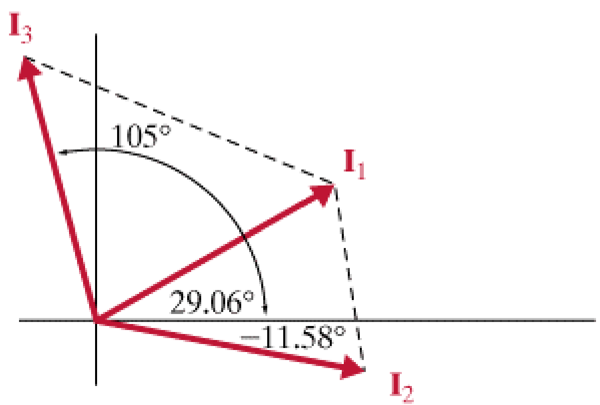
$$Z_{eq} = \frac{56 + j56}{8 + j2} = \frac{79.196\angle 45°}{8.246\angle 14.036°} = 9.604\angle 30.964°(\Omega)$$

$$I_1 = \frac{V_S}{Z_{eq}} = \frac{24\angle 60°}{9.604\angle 30.964°} = 2.498\angle 29.036°(A)$$

$$I_3 = \frac{j6}{8 + j2} I_1 = \frac{6\angle 90°}{8.246\angle 14.036} 2.498\angle 29.036(A)$$

$$I_2 = \frac{8 - j4}{8 + j2} I_1 = \frac{8.944\angle -26.565°}{8.246\angle 14.036°} 2.498\angle 29.036°(A)$$

$$I_1 = 2.5\angle 29.06° \qquad I_2 = 2.71\angle -11.58° \qquad I_3 = 1.82\angle 105°$$

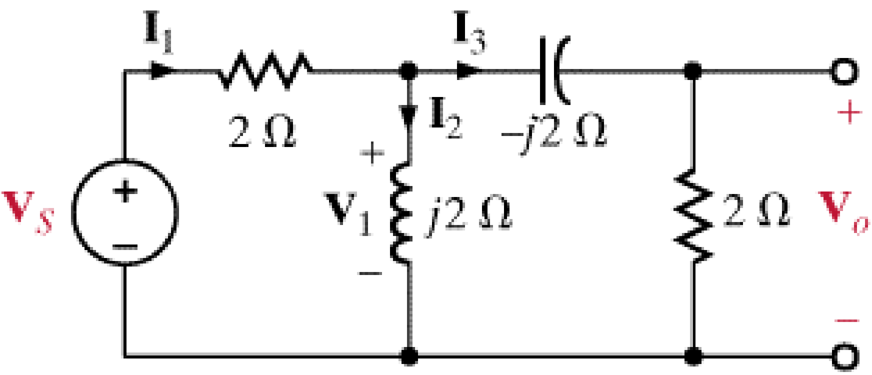


(b)

GEAUX

LEARNING EXTENSION

IF $V_O = 8\angle 45°$, COMPUTE V_S



THE PLAN...

COMPUTE I_3

COMPUTE V_1

COMPUTE I_2, I_1

COMPUTE V_S

$$I_3 = \frac{V_O}{2}(A) = 4\angle 45°(A)$$

$$V_1 = (2 - j2)I_3 = \sqrt{8}\angle -45° \times 4\angle 45°$$

$$V_1 = 11.314\angle 0°(V)$$

$$I_2 = \frac{V_1}{j2} = \frac{11.314\angle 0°}{2\angle 90°} = 5.657\angle -90°(A)$$

$$I_1 = I_2 + I_3 = 5.657\angle -90° + 4\angle 45°$$

$$I_1 = -j5.657 + (2.828 + j2.828)(A)$$

$$I_1 = 2.828 - j2.829(A)$$

$$V_S = 2I_1 + V_1 = 2(2.828 - j2.829) + 11.314\angle 0°$$

$$V_S = 16.97 - j5.658(V)$$

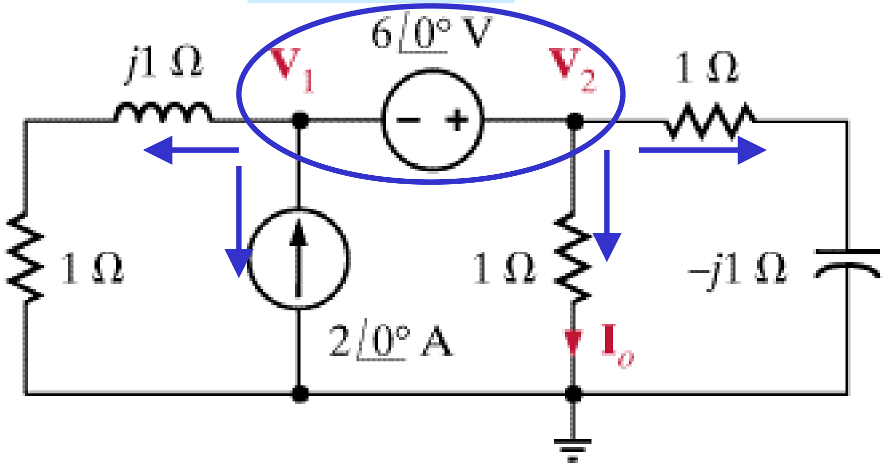
$$V_S = 17.888\angle -18.439°$$

GEAUX

ANALYSIS TECHNIQUES

PURPOSE: TO REVIEW ALL CIRCUIT ANALYSIS TOOLS DEVELOPED FOR RESISTIVE CIRCUITS; I.E., NODE AND LOOP ANALYSIS, SOURCE SUPERPOSITION, SOURCE TRANSFORMATION, THEVENIN'S AND NORTON'S THEOREMS.

COMPUTE I_0



1. NODE ANALYSIS

$$\frac{V_1}{1+j1} - 2\angle 0° + \frac{V_2}{1} + \frac{V_2}{1-j1} = 0$$

$$V_1 - V_2 = -6\angle 0°$$

$$I_0 = \frac{V_2}{1}(A)$$

$$\frac{V_2 - 6\angle 0°}{1+j1} - 2\angle 0° + V_2 + \frac{V_2}{1-j1} = 0$$

$$V_2\left[\frac{1}{1+j1} + 1 + \frac{1}{1-j1}\right] = 2 + \frac{6}{1+j1}$$

$$V_2 \frac{(1-j1)+(1+j1)(1-j1)+(1+j1)}{(1+j1)(1-j1)} = \frac{2(1+j1)+6}{1+j1}$$

$$V_2 \frac{4}{1-j} = 8 + j2$$

$$V_2 = \frac{(4+j)(1-j)}{2}$$

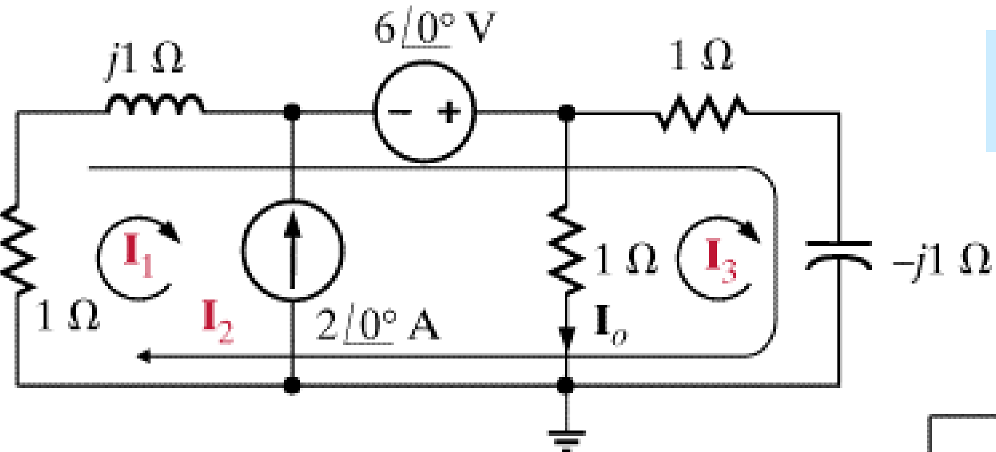
$$I_0 = \left(\frac{5}{2} - j\frac{3}{2}\right)(A)$$

$$I_0 = 2.92\angle -30.96°$$

NEXT: LOOP ANALYSIS

GEAUX

2. LOOP ANALYSIS



SOURCE IS NOT SHARED AND Io IS DEFINED BY ONE LOOP CURRENT

$I_0 = -I_3$

LOOP 1: $I_1 = -2\angle 0°$

LOOP 2: $(1+j)(I_1+I_2) - 6\angle 0° + (1-j)(I_2 + I$

LOOP 3: $(1-j)(I_2+I_3) + I_3 = 0$

MUST FIND I_3

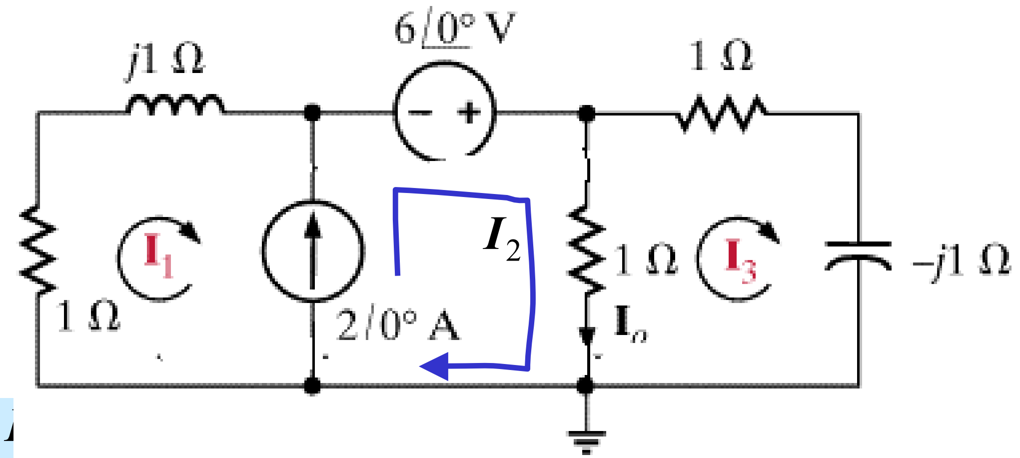
$2I_2 + (1-j)I_3 = 6 - (1+j)(-2)$ /* $(1-j)$

$(1-j)I_2 + (2-j)I_3 = 0$ /* (-2)

$\left((1-j)^2 - 2(2-j)\right)I_3 = (1-j)(8+2j)$

$I_3 = \dfrac{10-6j}{-4}$ $I_0 = -\dfrac{5}{2} + \dfrac{3}{2}j(A)$

ONE COULD ALSO USE THE SUPERMESH TECHNIQUE



CONSTRAINT: $I_1 - I_2 = -2\angle 0°$

SUPERMESH: $(1+j)I_1 + 6\angle 0° + (I_2 - I_3) = 0$

MESH 3: $(I_3 - I_2) + (1-j)I_3 = 0$

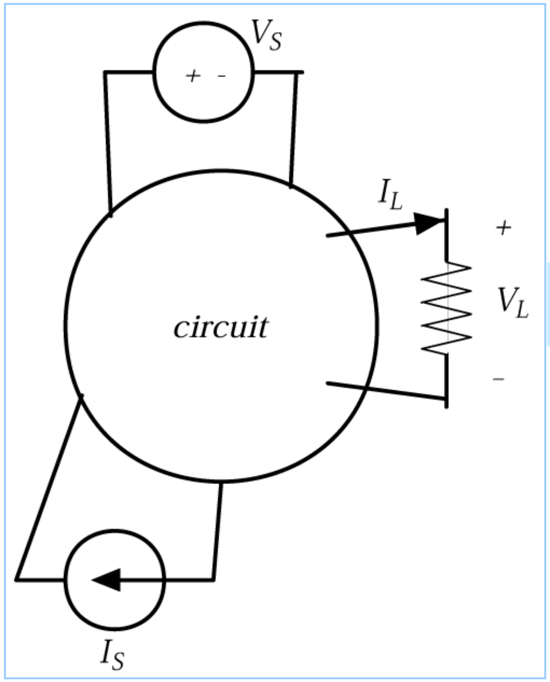
$I_0 = I_2 - I_3$

NEXT: SOURCE SUPERPOSITION

GEAUX

SOURCE SUPERPOSITION

Circuit with voltage source set to zero (SHORT CIRCUITED)



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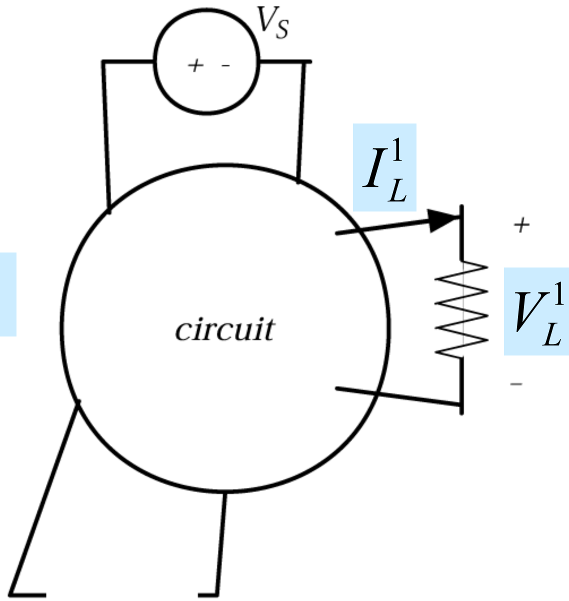

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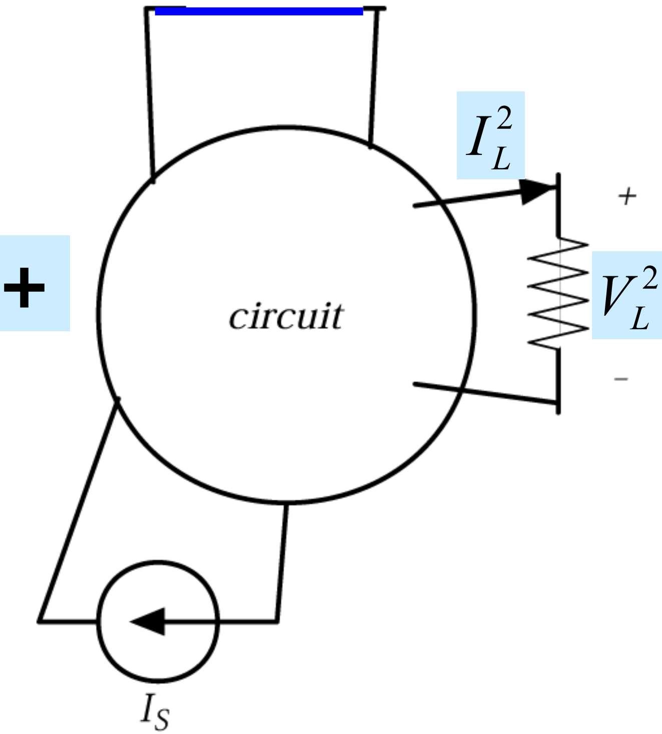


Circuit with current source set to zero(OPEN)

Due to the linearity of the models we must have

$$I_L = I_L^1 + I_L^2 \qquad V_L = V_L^1 + V_L^2$$

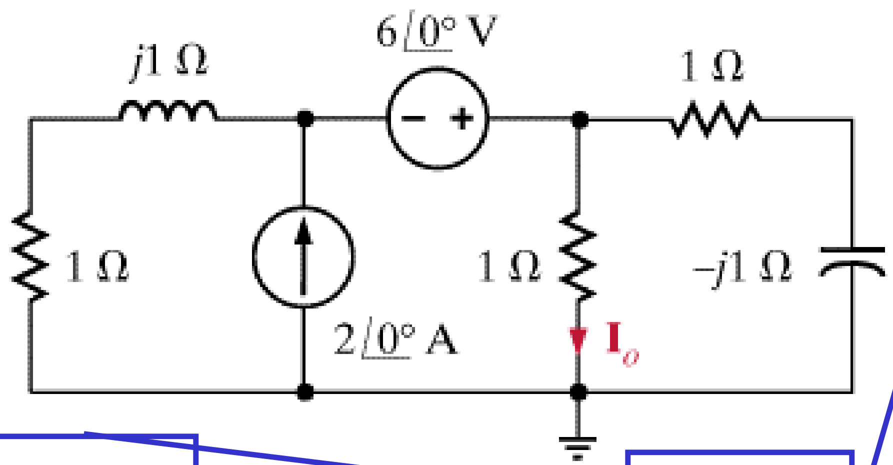
Principle of Source Superposition

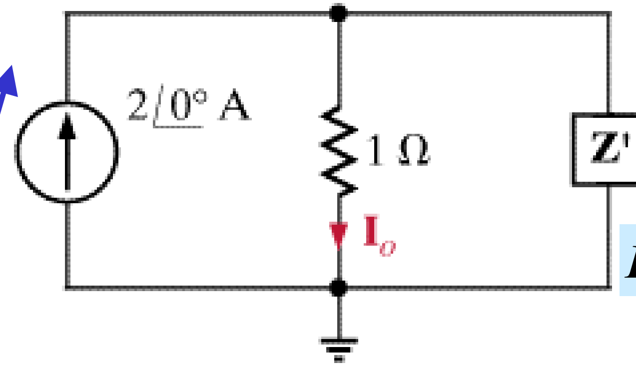
The approach will be useful if solving the two circuits is simpler, or more convenient, than solving a circuit with two sources

We can have any combination of sources. And we can partition any way we find convenient

GEAUX

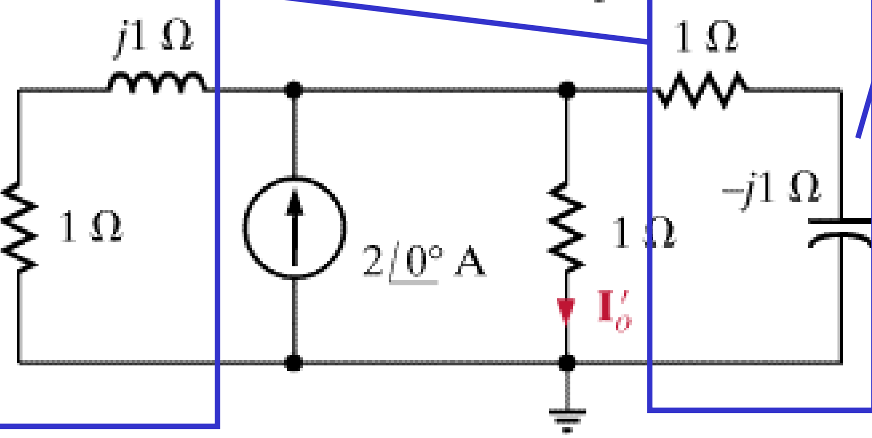
3. SOURCE SUPERPOSITION





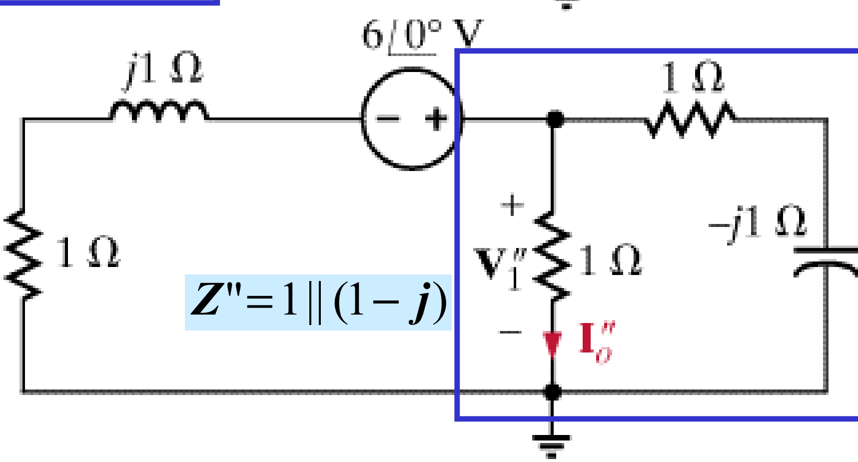
$$I_0' = 1\angle 0°(A)$$

$$Z' = (1+j)\,\|\,(1-j) = \frac{(1+j)(1-j)}{(1+j)-(1-j)} = 1$$



COULD USE SOURCE TRANSFORMATION TO COMPUTE I_0''

$$V_1'' = \frac{Z''}{Z''+1+j}6\angle 0°(V) \qquad I_0'' = \frac{Z''}{Z''+1+j}6\angle 0°(A)$$



$$Z'' = 1\,\|\,(1-j)$$

$$Z'' = \frac{1-j}{2-j}$$

$$I_0'' = \frac{\frac{1-j}{2-j}}{\frac{1-j}{2-j}+1+j}6(A)$$

$$I_0'' = \frac{1-j}{(1-j)+3+j}6$$

$$I_0'' = \frac{6}{4} - \frac{6}{4}j(A)$$

$$I_0 = I_0' + I_0'' = \left(\frac{5}{2} - \frac{3}{2}j\right)(A)$$

NEXT: SOURCE TRANSFORMATION

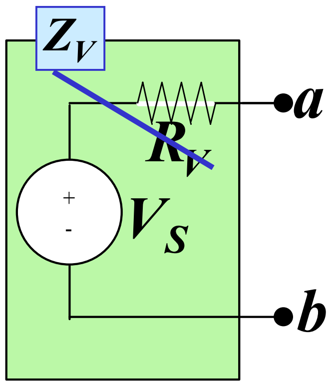
GEAUX

Source transformation is a good tool to reduce complexity in a circuit ...

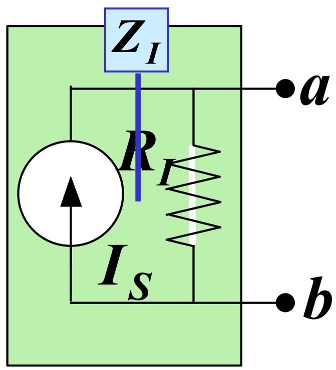
WHEN IT CAN BE APPLIED!!

"ideal sources" are not good models for real behavior of sources

A real battery does not produce infinite current when short-circuited



Improved model for voltage source



Improved model for current source

THE MODELS ARE EQUIVALENTS WHEN

$R_V = R_I = R$

$V_S = RI_S$

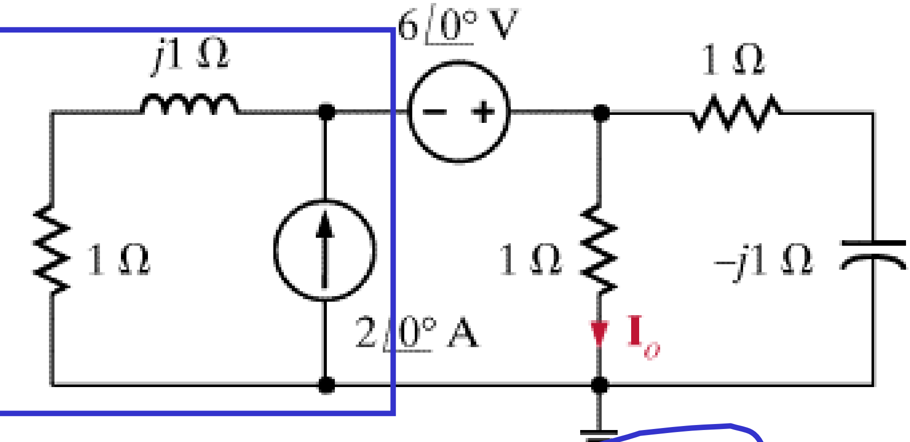
$Z_V = Z_I = Z$

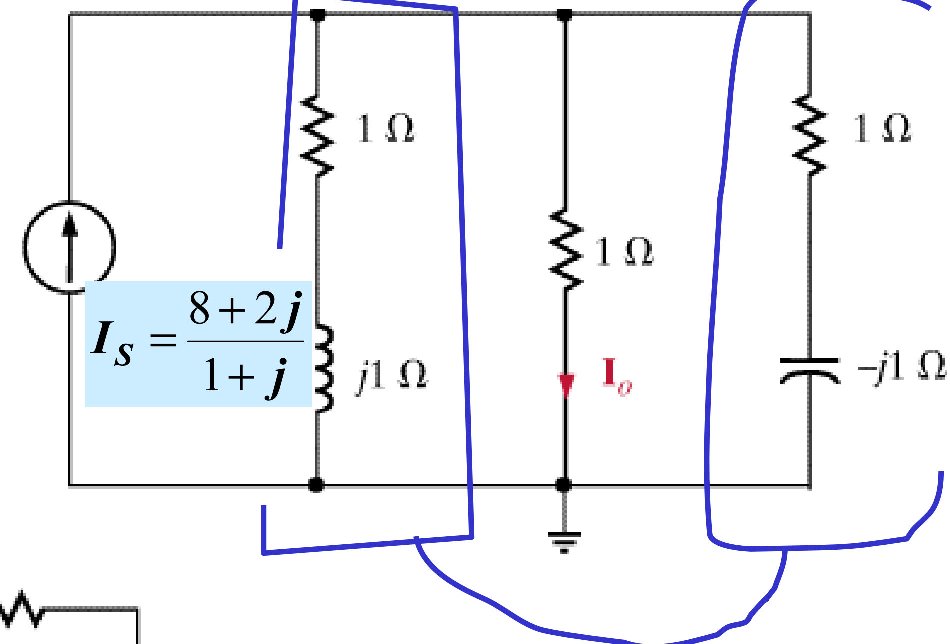
$V_S = ZI_S$

Source Transformationcan be used to determine the Thevenin or Norton Equivalent...

BUT THERE MAY BE MORE EFFICIENT TECHNIQUES

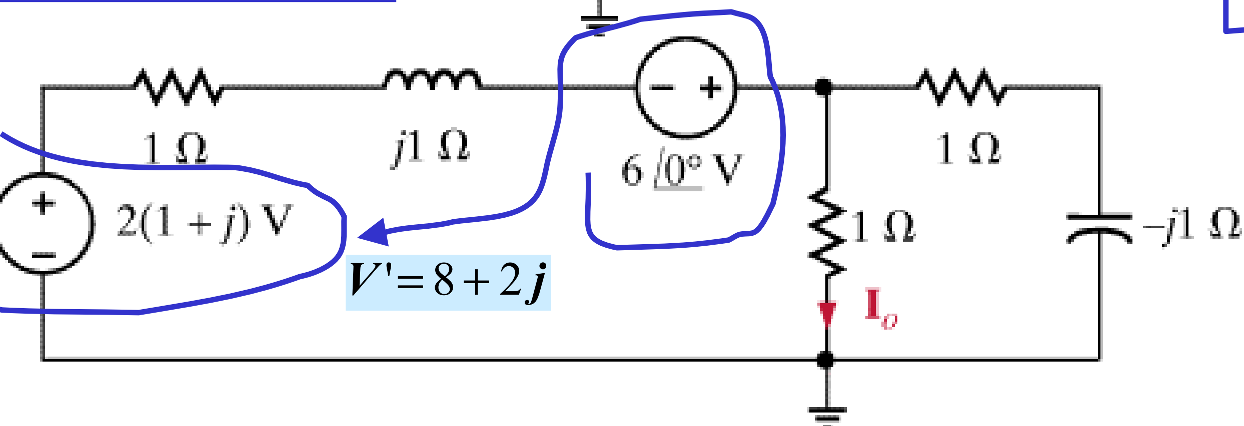
4. SOURCE TRANSFORMATION





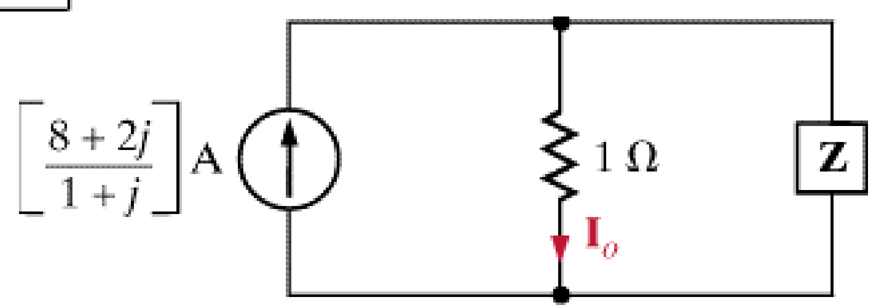
$$I_S = \frac{8+2j}{1+j}$$

$$Z = (1+j)\,\|\,(1-j) = 1\Omega$$



$$V' = 8+2j$$

Now a voltage to current transformation

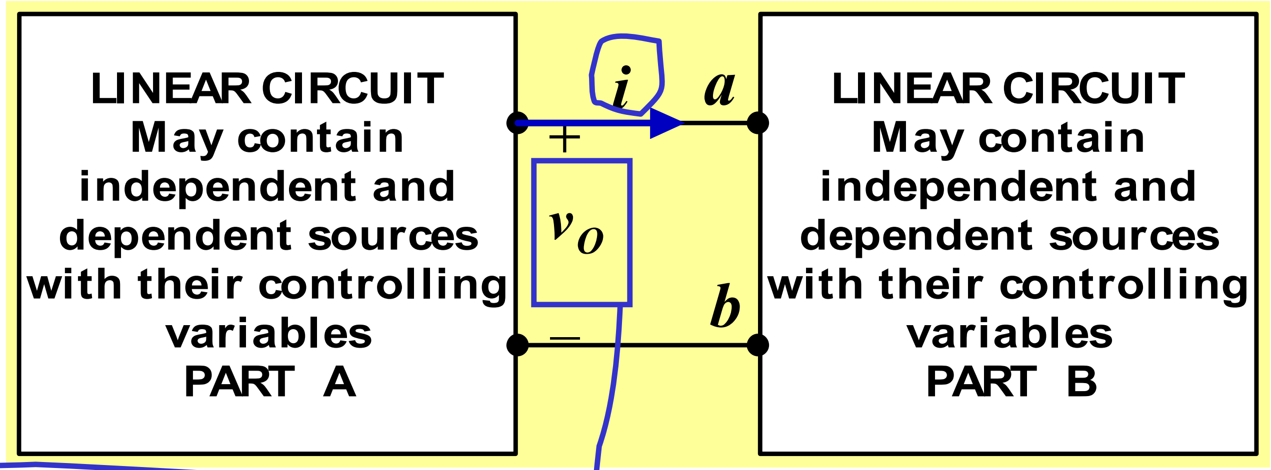


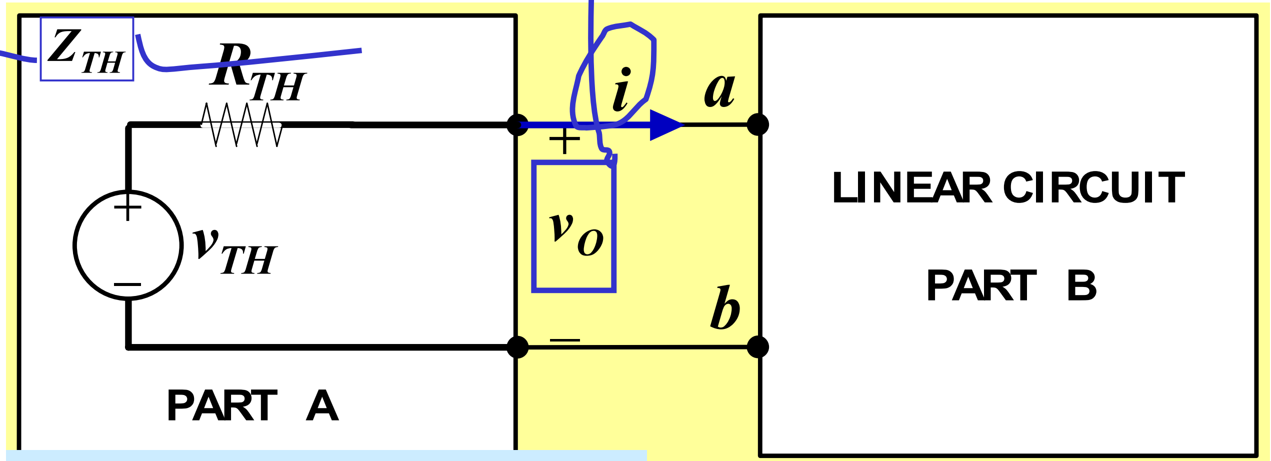
NEXT: THEVENIN

$$I_0 = \frac{I_S}{2} = \frac{4+j}{1+j} = \frac{(4+j)(1-j)}{(1+j)(1-j)} = \frac{5-3j}{2}$$

GEAUX

THEVENIN'S EQUIVALENCE THEOREM





Thevenin Equivalent Circuit

for PART A

Phasor

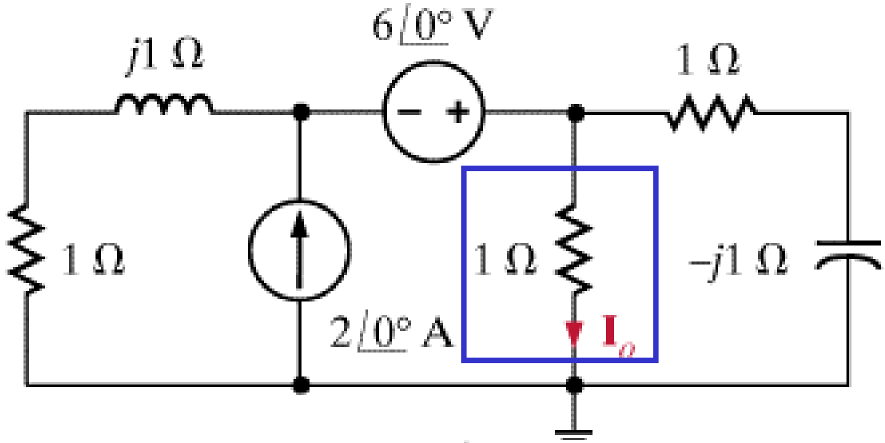
Impedance

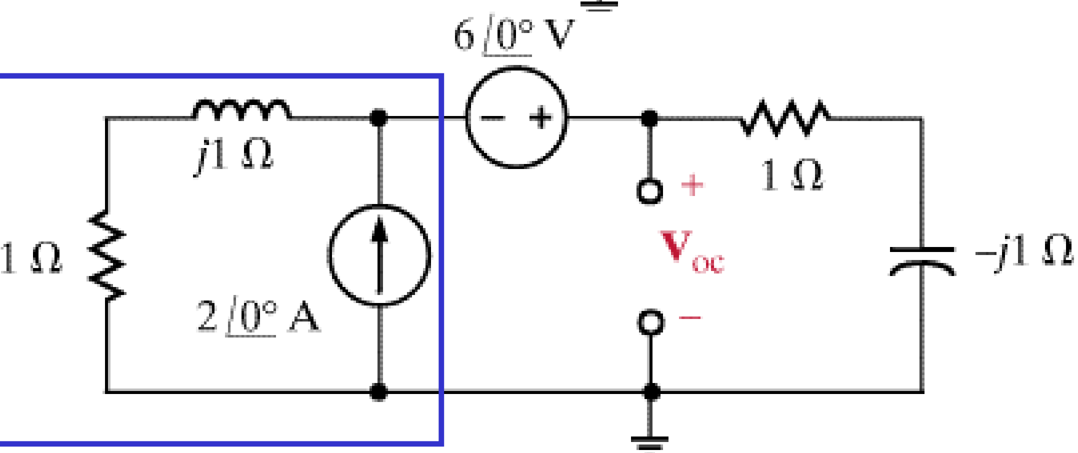
v_{TH} Thevenin Equivalent Source

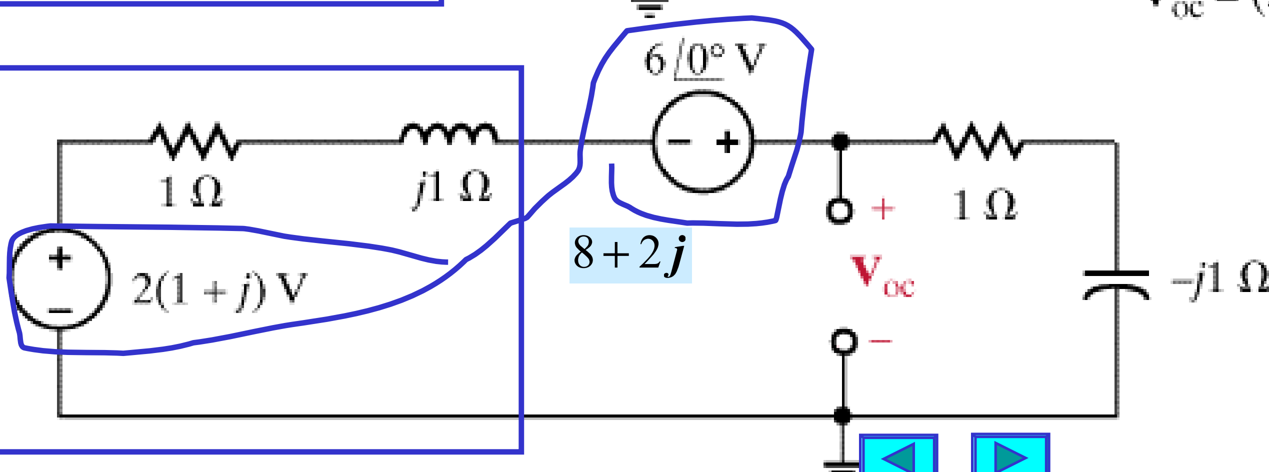
R_{TH} Thevenin Equivalent Resistance

GEAUX

5. THEVENIN ANALYSIS

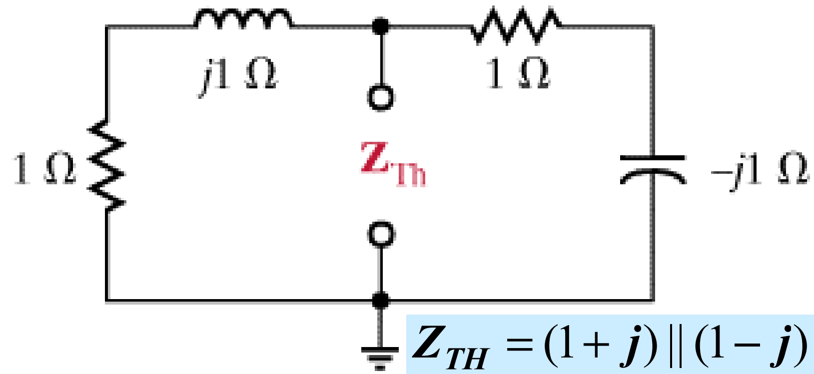




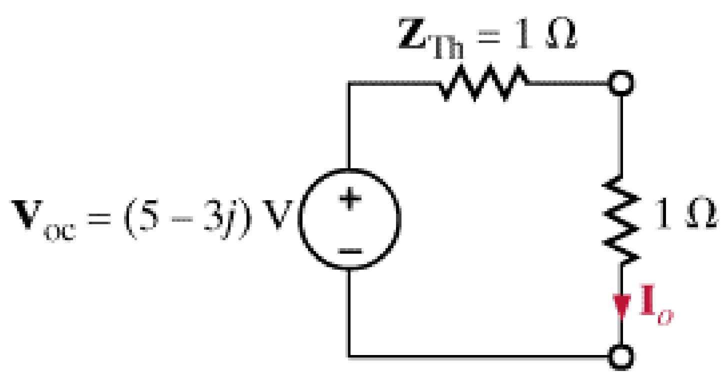


Voltage Divider

$$V_{OC} = \frac{1-j}{(1+j)+(1-j)}(8+2j) = \frac{10-6j}{2}$$



$$Z_{TH} = (1+j) \| (1-j) = 1\Omega$$

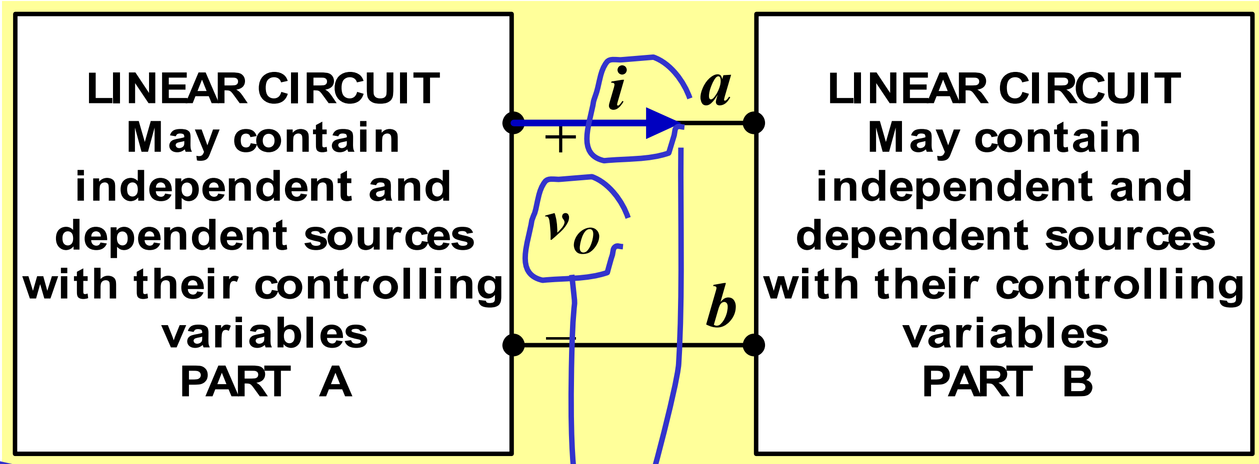


$$I_0 = \frac{5-3j}{2}(A)$$

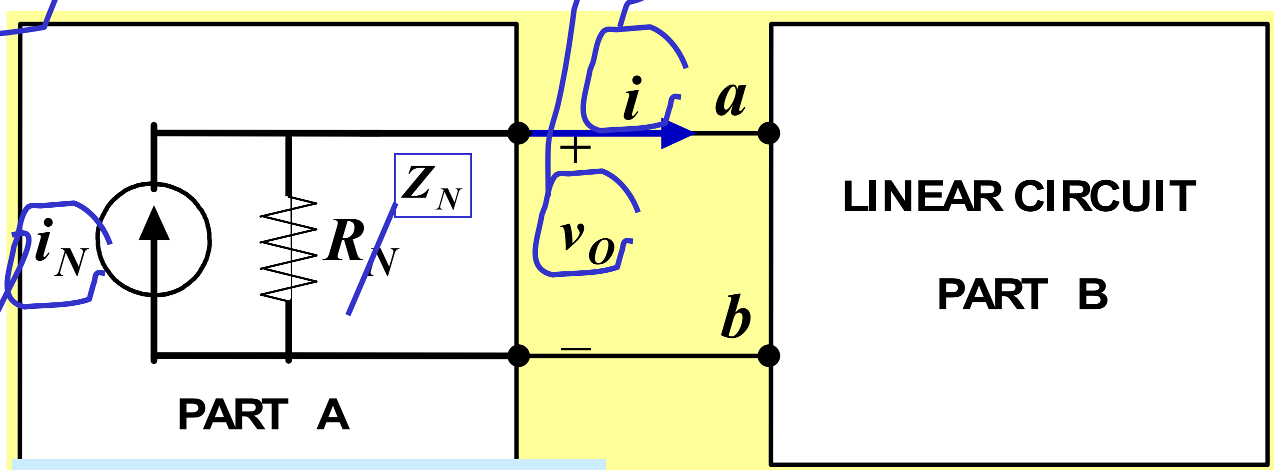
NEXT: NORTON

GEAUX

NORTON'S EQUIVALENCE THEOREM



Phasors



Norton Equivalent Circuit for PART A

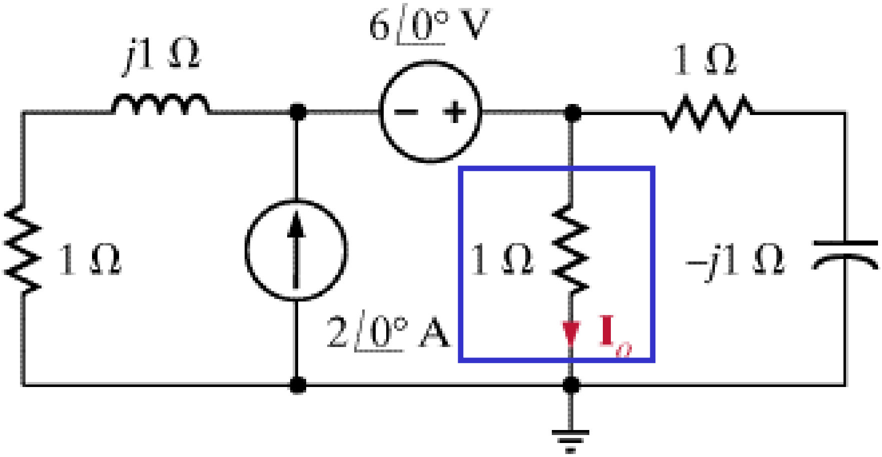
i_N Thevenin Equivalent Source

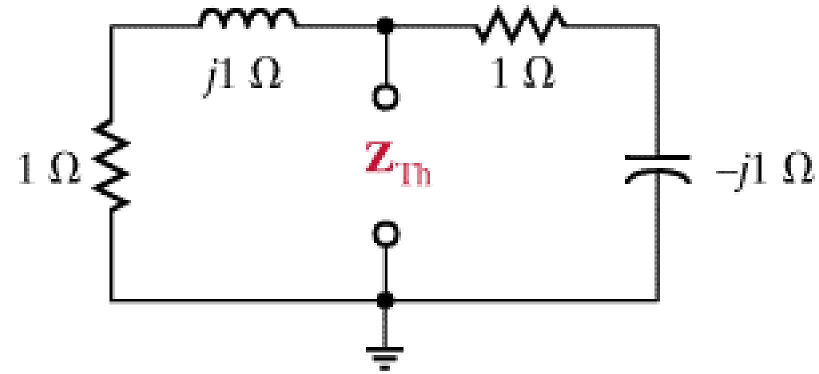
R_N Z_N Thevenin Equivalent Resistance

Impedance

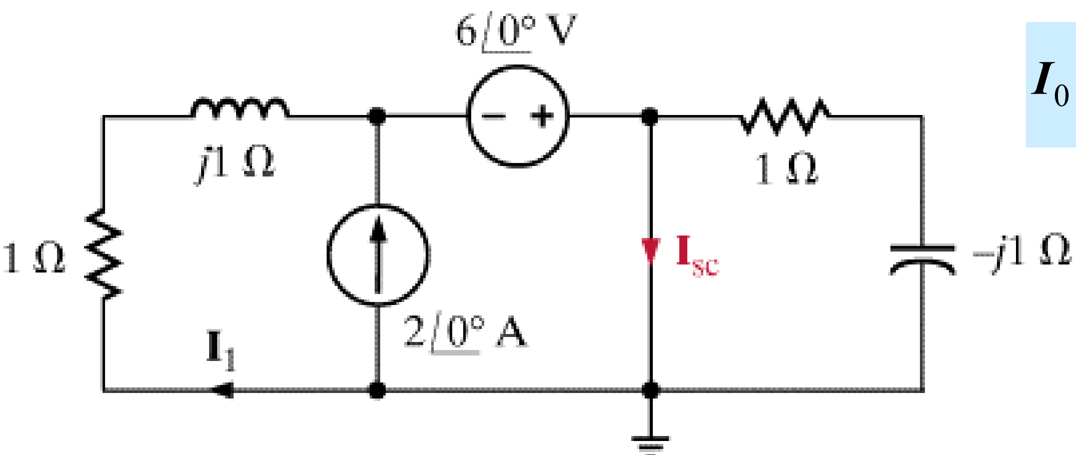
GEAUX

6. NORTON ANALYSIS



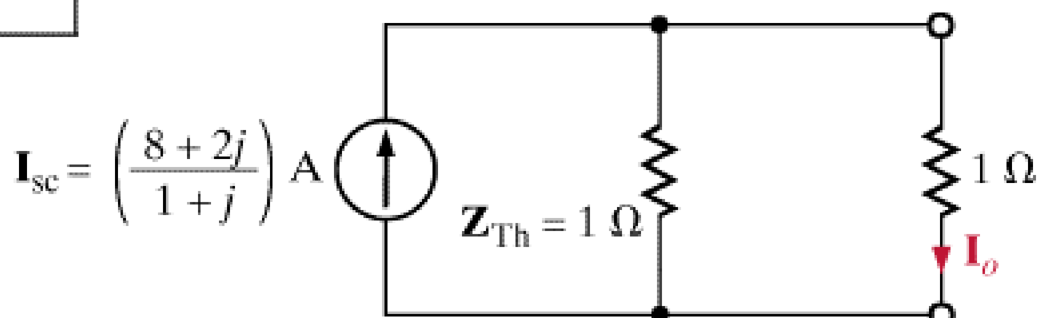


$$Z_{TH} = (1+j)\,||\,(1-j) = 1\Omega$$



$$I_0 = \frac{I_{SC}}{2} = \frac{4+j}{1-j} = \frac{(4+j)(1-j)}{(1+j)(1-j)} = \frac{5-3j}{2}$$

Possible techniques: loops, source transformation, superposition



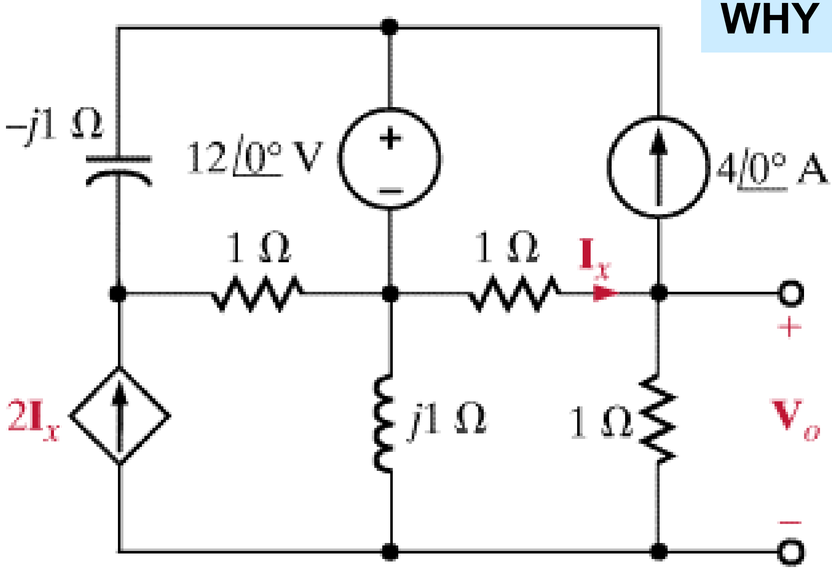
BY SUPERPOSTION

$$I_{SC} = 2\angle 0^\circ + \frac{6\angle 0^\circ}{1+j} = \frac{8+2j}{1+j}(A)$$

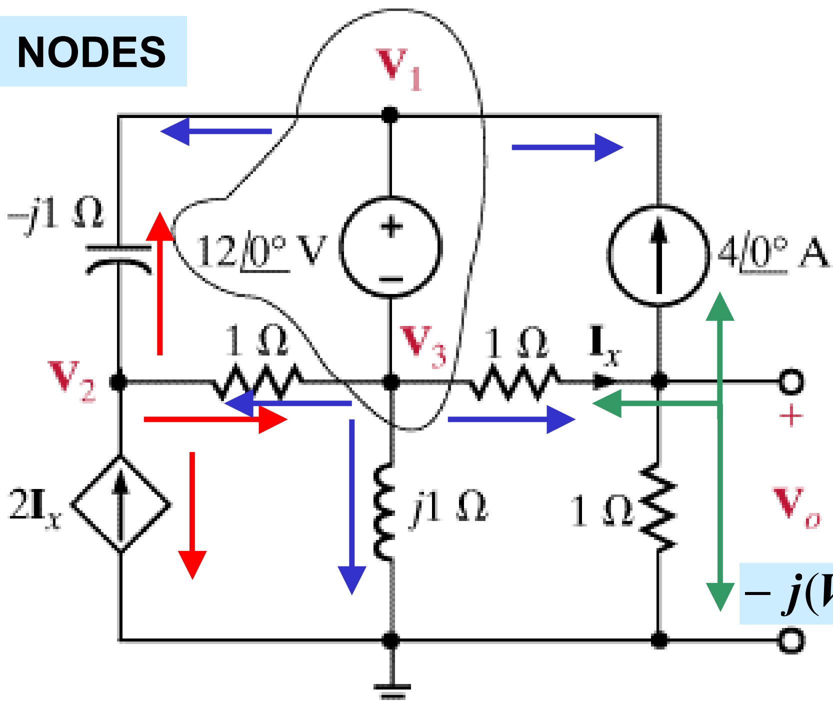
GEAUX

LEARNING EXAMPLE FIND V_0 USING NODES, LOOPS, THEVENIN, NORTON

WHY SKIP SUPERPOSITION AND TRANSFORMATION?



NODES



Supernode constraint : $V_1 - V_3 = 12\angle 0°$

KCL @ Supernode

$$-4\angle 0° + \frac{V_3 - V_0}{1} + \frac{V_3 - V_2}{1} + \frac{V_1 - V_2}{-j} + \frac{V_3}{j} = 0$$

KCL@V_2

$$\frac{V_2 - V_1}{-j} - 2I_x + \frac{V_2 - V_3}{1} = 0$$

KCL@ V_0

$$\frac{V_0}{1} + \frac{V_0 - V_3}{1} + 4\angle 0° = 0 \quad \Rightarrow V_3 = 2V_0 + 4$$

Controlling variable

$$I_x = \frac{V_3 - V_0}{1}$$

$$V_1 = V_3 + 12$$

$$V_1 = 2V_0 + 16$$

$$V_3 - V_0 = V_0 + 4$$

$$j(V_2 - 2V_0 - 16) - 2(V_0 + 4) + (V_2 - 2V_0 - 4) = 0$$

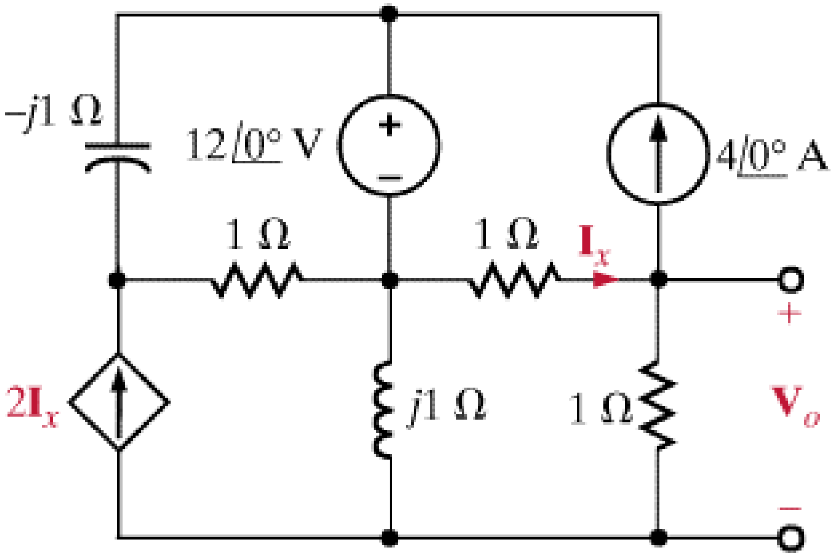
$$-j(V_2 - 2V_0 - 16) - (V_2 - 2V_0 - 4) + (V_0 + 4) - j(2V_0 + 4) = 4$$

Adding: $V_0 = -\dfrac{8 + 4j}{1 + 2j}$

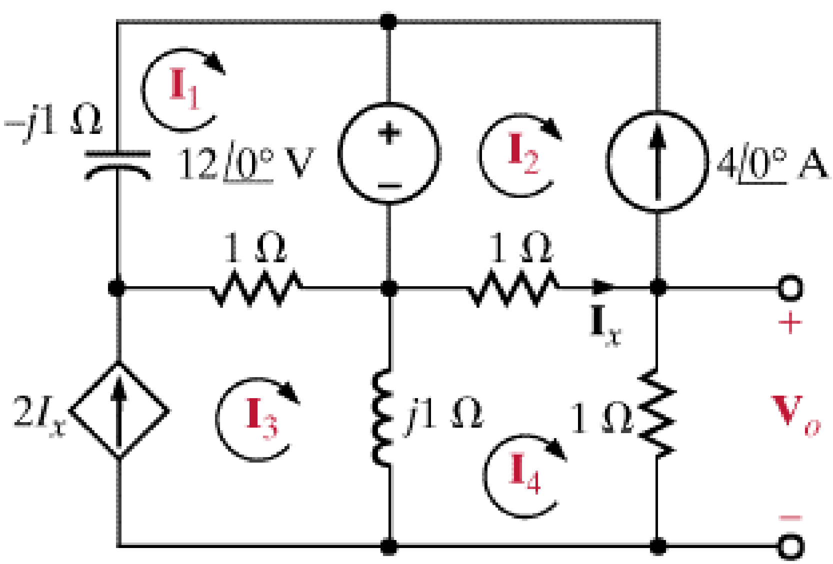
Notice choice of ground

GEAUX

LOOP ANALYSIS



MESH CURRENTS ARE ACCEPTABLE



MESH CURRENTS DETERMINED BY SOURCES

$$I_2 = -4\angle 0^\circ$$

$$I_3 = 2I_x \quad \Rightarrow I_3 = 2(I_4 + 4)$$

MESH 1:

$$-jI_1 + 12\angle 0^\circ + 1(I_1 - I_3) = 0$$

MESH 4:

$$1(I_4 - I_2) + 1 \times I_4 + j(I_4 - I_3) = 0$$

CONTROLLING VARIABLE: $I_x = I_4 - I_2$

VARIABLE OF INTEREST: $V_0 = 1 \times I_4 (V)$

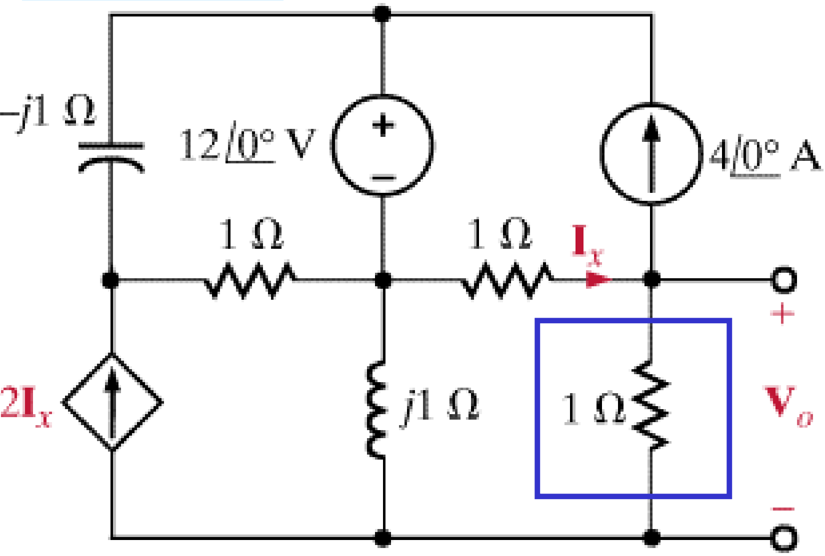
$$I_4 + 4 + I_4 + j(I_4 - 2(I_4 + 4)) = 0$$

$$(2 - j)I_4 = -(4 - 8j) \Rightarrow I_4 = -\frac{4 - 8j}{2 - j} \times \frac{j}{j}$$

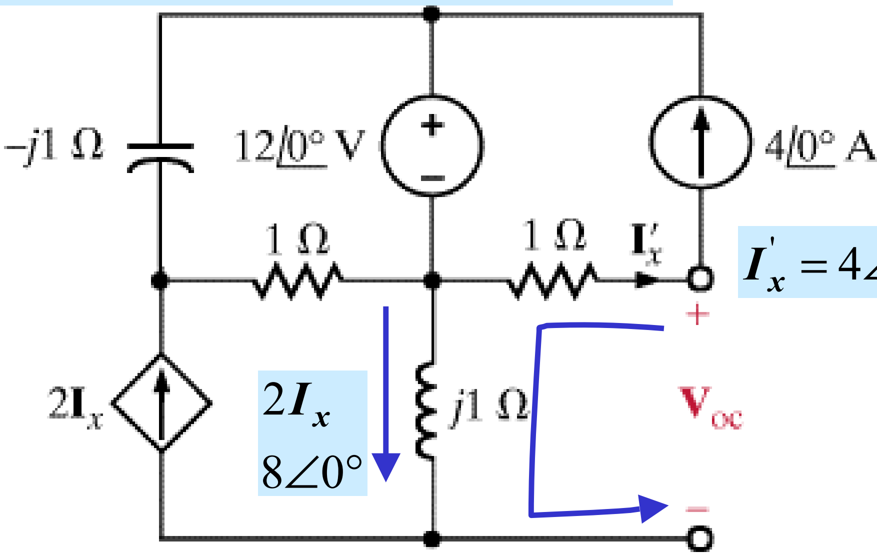
$$V_0 = -\frac{8 + 4j}{1 + 2j}$$

GEAUX

THEVENIN



FOR OPEN CIRCUIT VOLTAGE



$I'_x = 4\angle 0°$

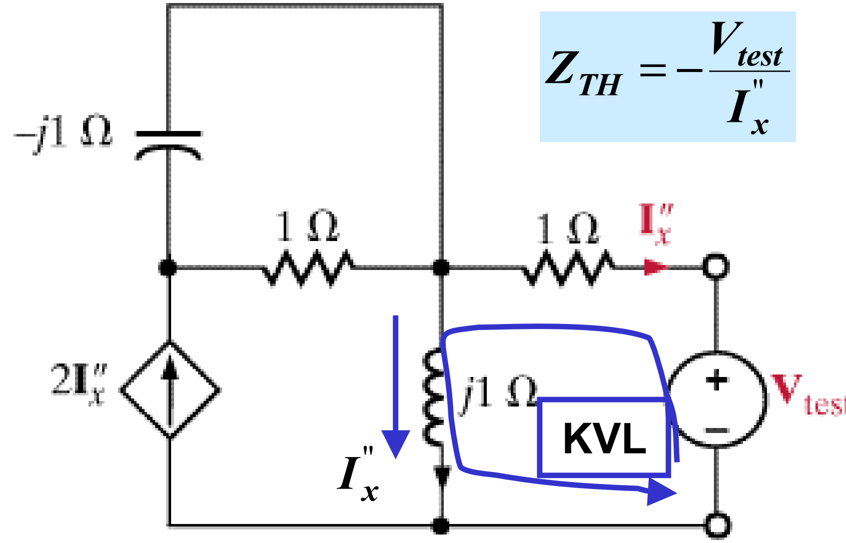
$V_{OC} = -4 + 8j(V)$

Alternative procedure to compute Thevenin impedance:

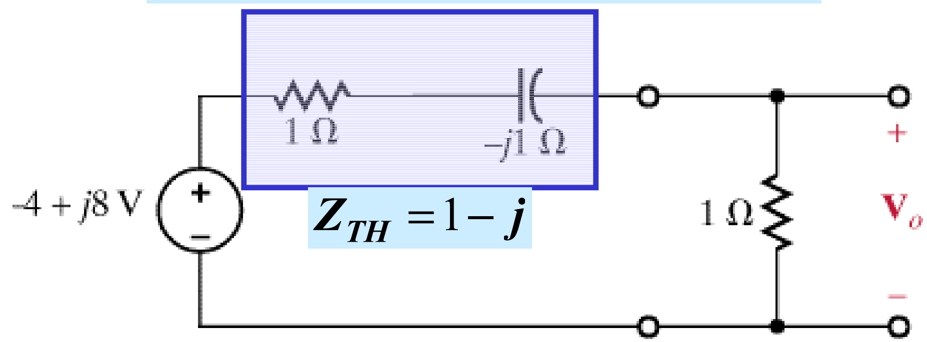
1. Set to zero all INDEPENDENT sources

2. Apply an external probe

$$Z_{TH} = -\frac{V_{test}}{I''_x}$$



$$V_{test} = -I''_x + jI''_x \Rightarrow Z_{TH} = 1 - j(\Omega)$$

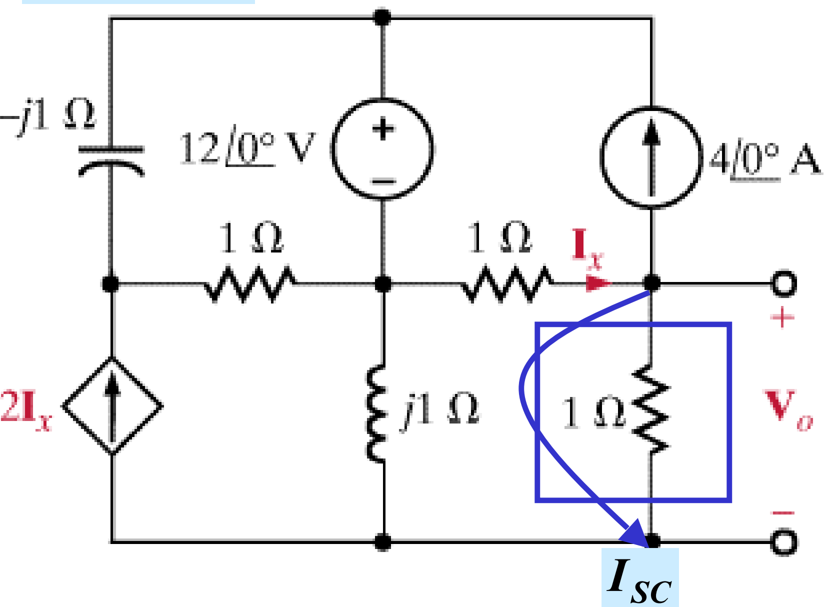


$Z_{TH} = 1 - j$

$$V_0 = \frac{1}{2-j}(-4+8j)(V)$$

GEAUX

NORTON



Supernode constraint

$$V_1 - V_3 = 12\angle 0^\circ \qquad \Rightarrow V_1 = V_3 + 12$$

KCL@ Supernode

$$\frac{V_3}{1} + \frac{V_3}{j} + \frac{V_3 - V_2}{1} + \frac{V_1 - V_2}{-j} - 4\angle 0^\circ = 0 \quad /\times j$$

$$\text{KCL@ } V_2 : \; -2I_X''' + \frac{V_2 - V_3}{1} + \frac{V_2 - V_1}{-j} = 0 \quad /\times(-j)$$

$$\text{Controlling Variable}: \; I_x''' = \frac{V_3}{1}$$

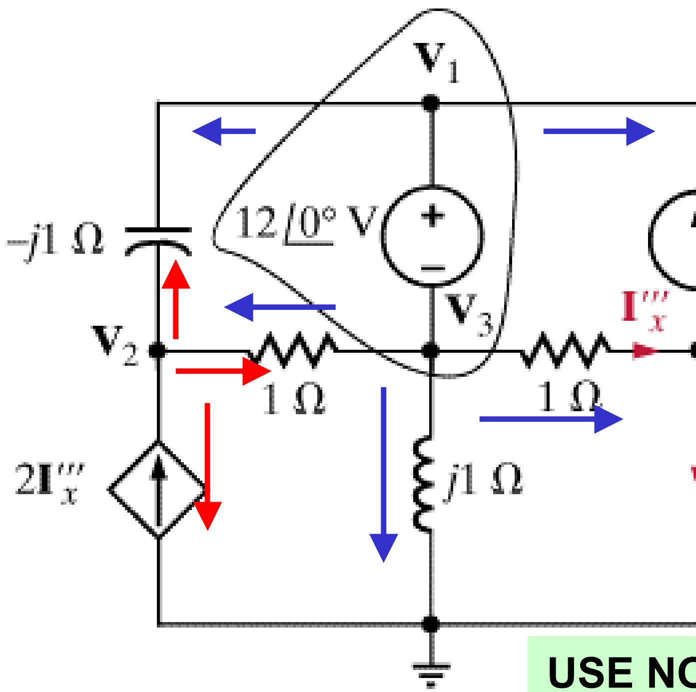
$$2jV_3 - j(V_2 - V_3) + (V_2 - V_3 - 12) = 0$$

$$(1-j)V_2 - (1-3j)V_3 = 12$$

$$(1+j)V_3 + jV_3 - jV_2 - (V_3 + 12) + V_2 = 4j$$

$$(1-j)V_2 + 2jV_3 = 12 + 4j$$

$$(1-j)V_3 = 4j \Rightarrow V_3 = \frac{4j}{1-j} \Rightarrow I_{SC} = \frac{-4+8j}{1-j}$$



$$I_x''' = \frac{V_3}{1}(A)$$

$$I_{SC} = I_x''' - 4$$

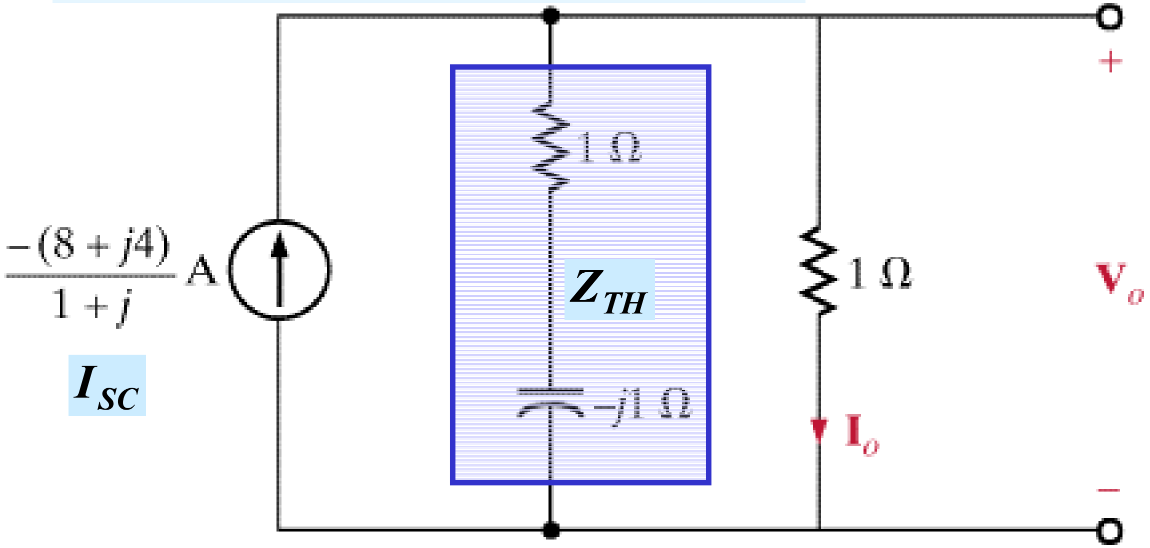
$$I_{SC} = \frac{(-4+8j)j}{(1-j)j} = -\frac{8+4j}{1+j}$$

Now we can draw the Norton Equivalent circuit ...

USE NODES

GEAUX

NORTON'S EQUIVALENT CIRCUIT



$$V_0 = (1)I_0(V) = \frac{1-j}{2-j}\left(-\frac{8+4j}{1+j}\right)(V)$$

Current Divider

EQUIVALENCE OF SOLUTIONS

Using Norton's method

$$V_0 = -\frac{12-4j}{3+j} = -\frac{(8+4j)(1-j)}{(1+2j)(1-j)}$$

Using Thevenin's

$$V_0 = \frac{-4+8j}{2-j} \times \frac{j}{j}$$

Using Node and Loop methods

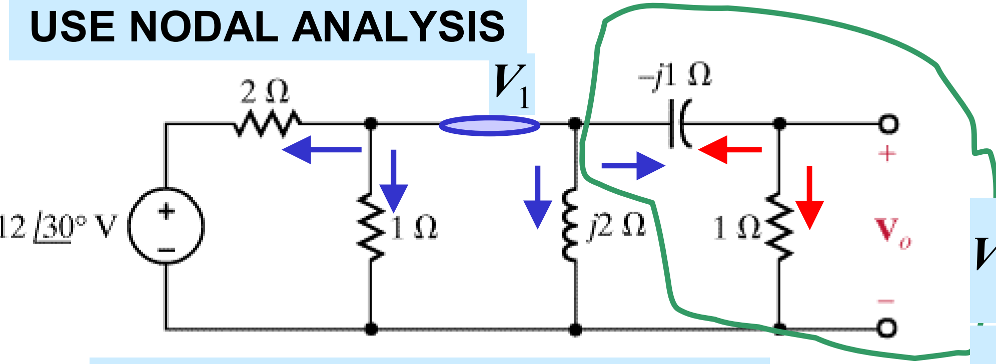
$$V_0 = -\frac{8+4j}{1+2j}$$

GEAUX

LEARNING EXTENSION

COMPUTE V_0

USE NODAL ANALYSIS



$$\frac{V_1 - 12\angle 30^\circ}{2} + \frac{V_1}{1} + \frac{V_1}{j2} + \frac{V_1 - V_0}{-j} = 0 \quad /\times 2j$$

$$\frac{V_0 - V_1}{-j} + \frac{V_0}{1} = 0 \Rightarrow V_1 = (1-j)V_0$$

$$j(V_1 - 12\angle 30^\circ) + 2jV_1 + V_1 - 2(V_1 - V_0) = 0$$

$$2V_0 + (1 - 2 + 2j + j)(1-j)V_0 = j12\angle 30^\circ$$

$$(2 + (-1+3j)(1-j))V_0 = 1\angle 90^\circ \times 12\angle 30^\circ$$

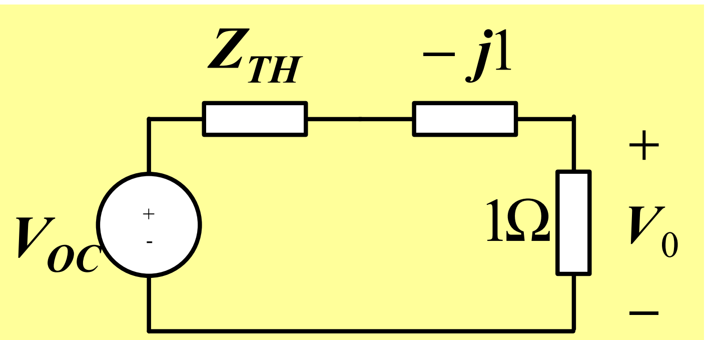
$$V_0 = \frac{12\angle 120^\circ}{4+4j} = \frac{12\angle 120^\circ}{5.66\angle 45^\circ} = 2.12\angle 75^\circ (V)$$

USE THEVENIN

$$Z_{TH} = 2 \| 1 \| j2 = \frac{4j/3}{2/3 + j2} = \frac{4j}{2+6j} = \frac{4j(2-6j)}{40}$$

$$V_{OC} = \frac{1 \| j2}{2 + (1 \| j2)} 12\angle 30^\circ = \frac{j2}{2(1+2j)+2j} 12\angle 30^\circ$$

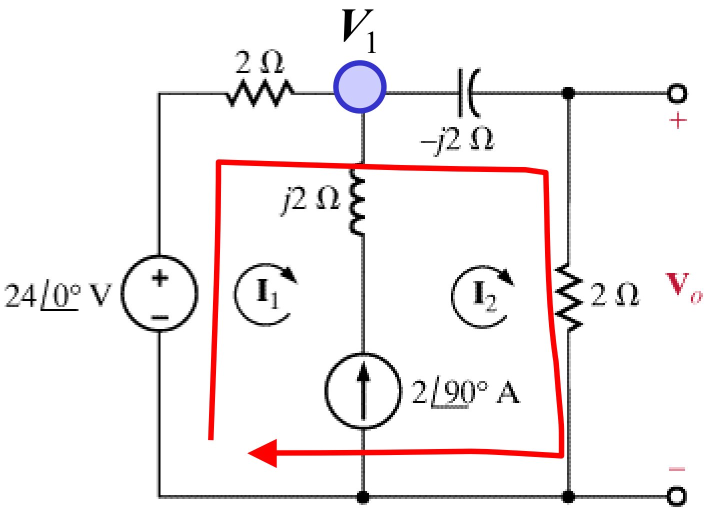
$$V_{OC} = \frac{24\angle 120^\circ}{2+6j} = \frac{12\angle 120^\circ}{1+3j}$$



$$V_0 = \frac{1}{Z_{TH} + 1 - j} V_{OC}$$

GEAUX

LEARNING EXTENSION COMPUTE V_0 USING MESH ANALYSIS



CONSTRAINT

$$-I_1 + I_2 = 2\angle 90^\circ \quad \Rightarrow I_1 = I_2 - 2j$$

SUPERMESH

$$-24\angle 0^\circ + 2I_1 - 2jI_2 + 2I_2 = 0$$

$$2(I_2 - 2j) + (2-2j)I_2 = 24 \Rightarrow (4-2j)I_2 = 24 + 4j$$

$$V_0 = 2I_2 = \frac{24+4j}{2-j} = \frac{24.33\angle 9.46^\circ}{2.24\angle -26.57^\circ} = 10.86\angle 36.03^\circ$$

USING NODES

$$\frac{V_1 - 24\angle 0^\circ}{2} - 2\angle 90^\circ + \frac{V_1}{2-2j} = 0$$

$$V_0 = \frac{2}{2-2j}V_1$$

USING SOURCE SUPERPOSITION

$$V_0^V = \frac{2}{2+2-2j}24\angle 0^\circ$$

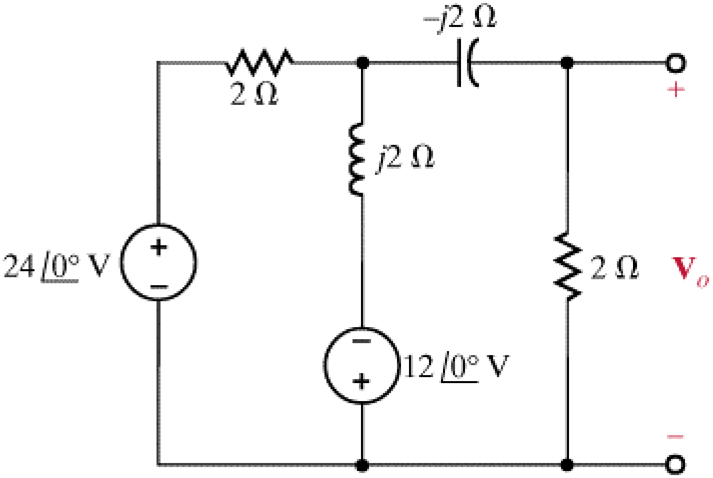
$$V_0^I = 2 \times \frac{2}{4-2j}2\angle 90^\circ$$

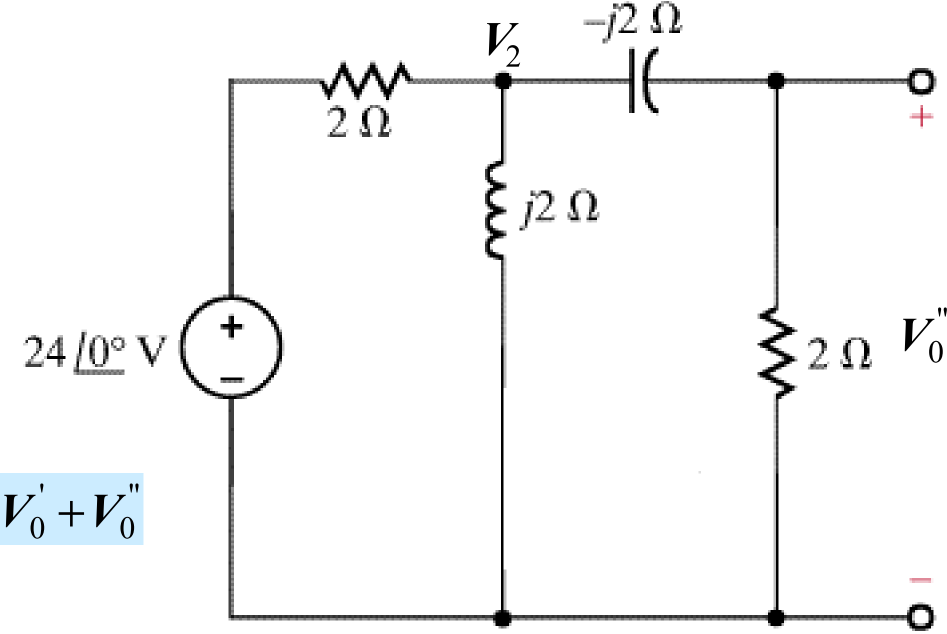
$$V_0 = V_0^V + V_0^I$$

GEAUX

LEARNING EXTENSION

COMPUTE V_0

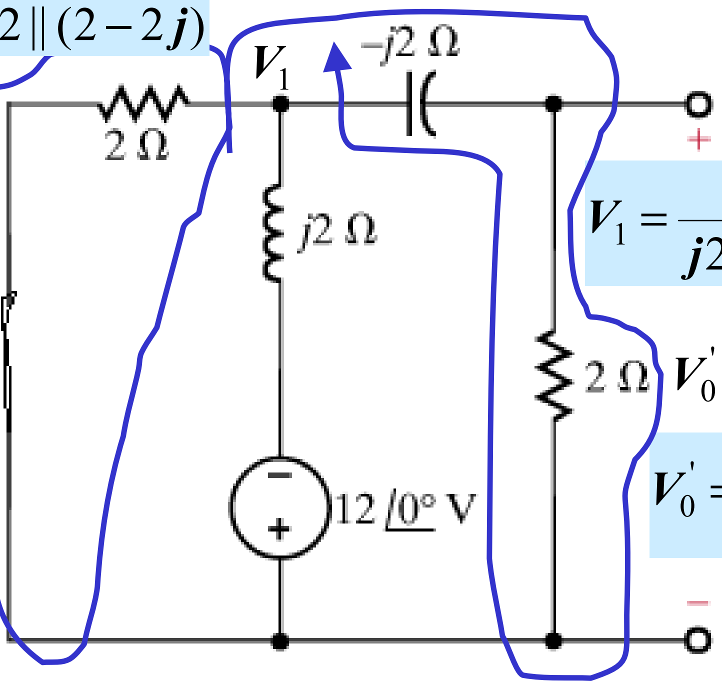




$$V_0 = V_0^{'} + V_0^{"}$$

1. USING SUPERPOSITION

$2 \| (2-2j)$



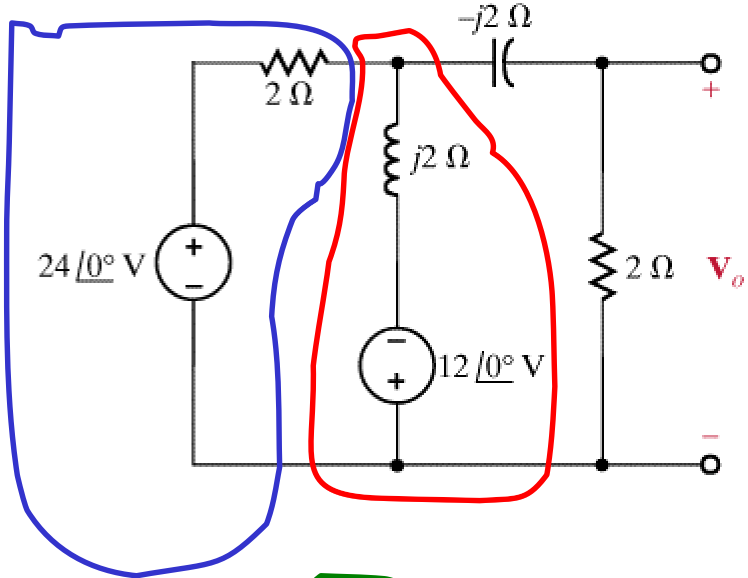
$$V_1 = \frac{2 \| (2-2j)}{j2 + (2 \| 2-2j)}(-12\angle 0°)$$

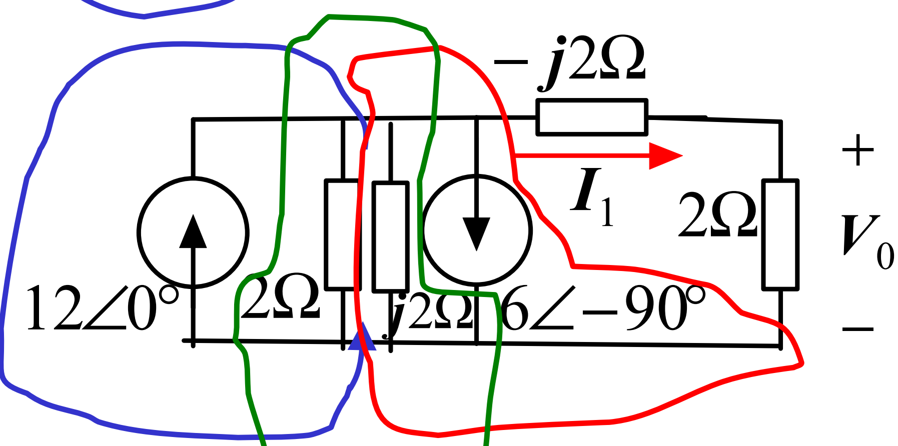
$$V_0^{'} = \frac{2}{2-2j} V_1$$

$$V_2 = \frac{(2j) \| (2-2j)}{2 + (2j \| (2-2j)}24\angle 0°$$

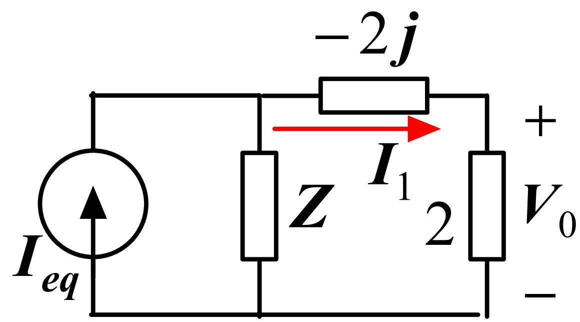
$$V_0^{"} = \frac{2}{2-2j} V_2$$

2. USE SOURCE TRANSFORMATION





$Z = 2 \parallel j2$

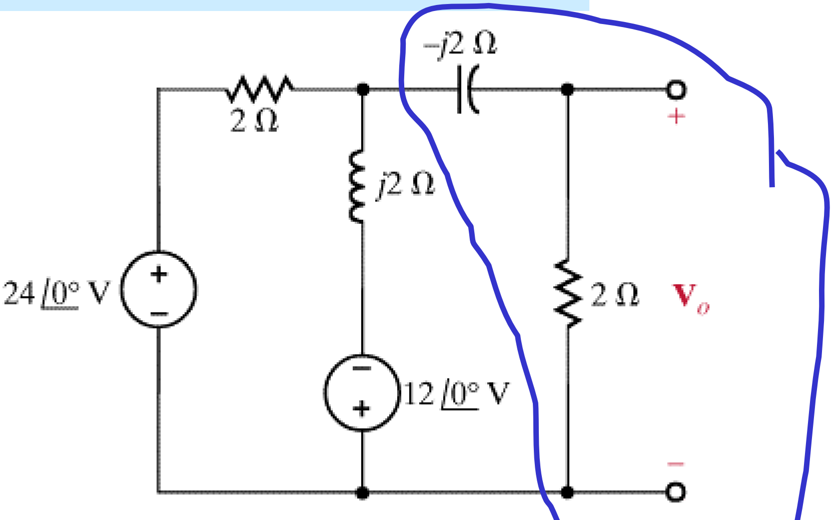


$$I_{eq} = 12\angle 0° - 6\angle -90° = 12 + 6j$$

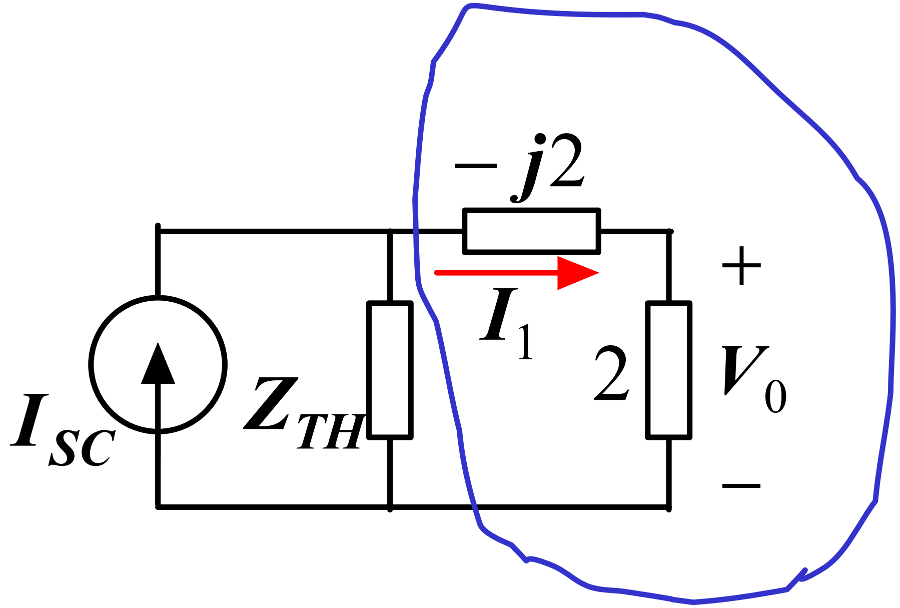
$$I_1 = \frac{Z}{Z + 2 - 2j} I_{eq}$$

$$V_0 = 2I_1$$

USE NORTON'S THEOREM

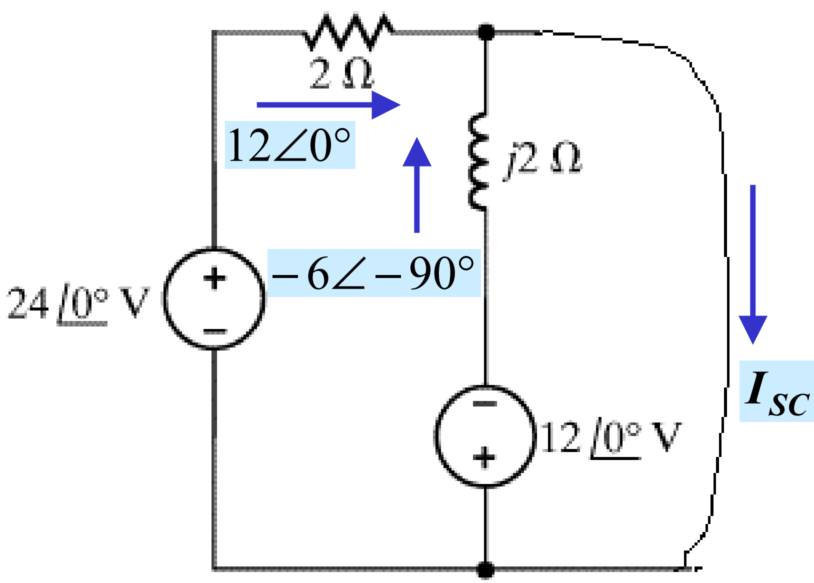


$Z_{TH} = 2 \,||\, j2$



$$I_1 = \frac{Z_{TH}}{Z_{TH} + 2 - 2j} I_{SC}$$

$$V_0 = 2I_1$$



GEAUX

USING MATLAB

MATLAB recognizes complex numbers in rectangular representation. It does NOT recognize Phasors

Unless previously re-defined, MATLAB recognizes "i" or "j" as imaginary units

```
» z2=3+4j

z2 =

   3.0000 + 4.0000i

» z1=4+6i

z1 =

   4.0000 + 6.0000i
```

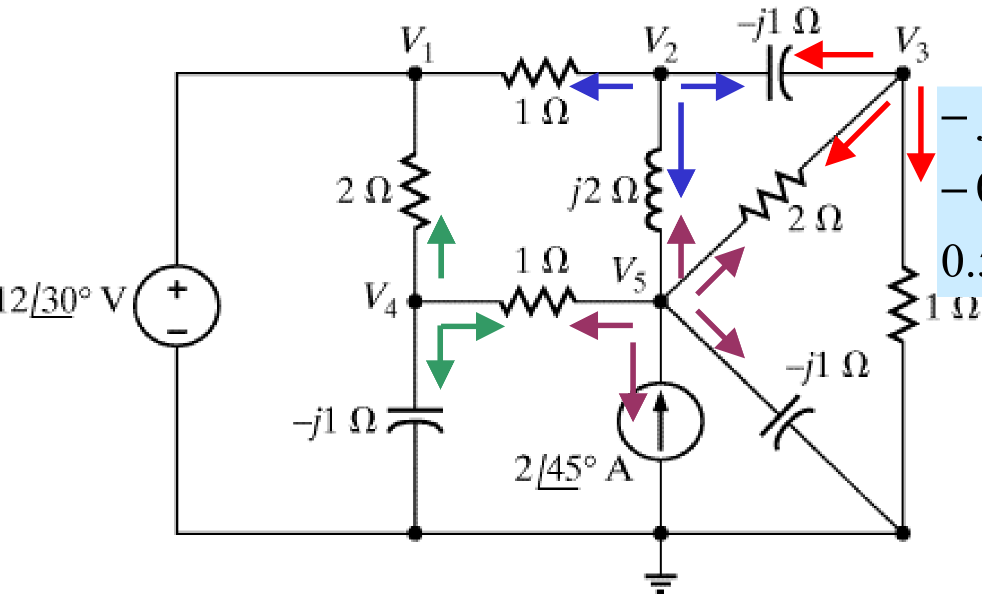
In its output MATLAB always uses "i" for the imaginary unit

Phasors ↔ Rectangular $z = 10\angle 45°$

```
» a=45; % angle in degrees
» ar=a*pi/180, %convert degrees to radians
ar =
    0.7854
» m=10; %define magnitude
» x=m*cos(ar); %real part
x =
    7.0711
» y=m*sin(ar); %imaginary part
y =
    7.0711
» z=x+i*y
z =
   7.0711 + 7.0711i
z =  7.0711 + 7.0711i;
» mp=abs(z); %compute magnitude
mp =
    10
» arr=angle(z); %compute angle in RADIANS
arr =
0.7854
» adeg=arr*180/pi; %convert to degres
adeg =
    45
x=real(z)
x=
   7.0711
y=imag(z)
y=
    .70711
```

LEARNING EXAMPLE

COMPUTE ALL NODE VOLTAGES



$$V_1 = 12\angle 30°$$

$$-V_1 + (1 + j - 0.5j)V_2 - jV_3 - 0.5jV_5 = 0$$

$$-jV_2 + (j + 0.5 + 1)V_3 - 0.5V_5 = 0$$

$$-0.5V_1 + (0.5 + 1 + j)V_4 - V_5 = 0$$

$$0.5jV_2 - 0.5V_3 - V_4 + (1 - 0.5j + 0.5 + j)V_5 = 2\angle 45°$$

$$V_1 = 12\angle 30°$$

$$\frac{V_2 - V_1}{1} + \frac{V_2 - V_3}{-j1} + \frac{V_2 - V_5}{j2} = 0$$

$$\frac{V_3 - V_2}{-j1} + \frac{V_3 - V_5}{2} + \frac{V_3}{1} = 0$$

$$\frac{V_4 - V_1}{2} + \frac{V_4 - V_5}{1} + \frac{V_4}{-j1} = 0$$

$$-2\angle 45° + \frac{V_5 - V_4}{1} + \frac{V_5 - V_2}{j2} + \frac{V_5 - V_3}{2} + \frac{V_5}{-j1} = 0$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ -1 & 1 + j0.5 & -j1 & 0 & j0.5 \\ 0 & -j1 & 1.5 + j1 & 0 & -0.5 \\ -0.5 & 0 & 0 & 1.5 + j1 & -1 \\ 0 & j0.5 & -0.5 & -1 & 1.5 + j0.5 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \end{bmatrix} = \begin{bmatrix} 12\angle 30° \\ 0 \\ 0 \\ 0 \\ 2\angle 45° \end{bmatrix}$$

$$YV = I_R$$

$$V = Y^{-1} I_R$$

GEAUX

```
%example7p17
%define the RHS vector.
ir=zeros(5,1); %initialize and define non zero values
ir(1)=12*cos(30*pi/180)+j*12*sin(30*pi/180);
ir(5)=2*cos(pi/4)+j*2*sin(pi/4), %echo the vector
%now define the matrix
y=[1,0,0,0,0; %first row
   -1,1+0.5j,-j,0,0.5j; %second row
   0,-j,1.5+j,0,-0.5; %third row
   -0.5,0,0,1.5+j,-1; %fourth row
   0,0.5i,-0.5,-1,1.5+0.5i] %last row and do echo
v=y\ir %solve equations and echo the answer
```

Echo of Answer

```
v =

  10.3923 + 6.0000i
   7.0766 + 2.1580i
   1.4038 + 2.5561i
   3.7661 - 2.9621i
   3.4151 - 3.6771i
```

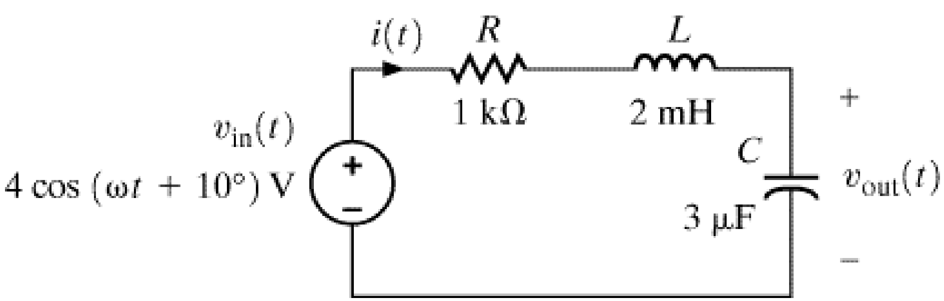
Echo of RHS

```
ir =
  10.3923 + 6.0000i
        0
        0
        0
   1.4142 + 1.4142i
```

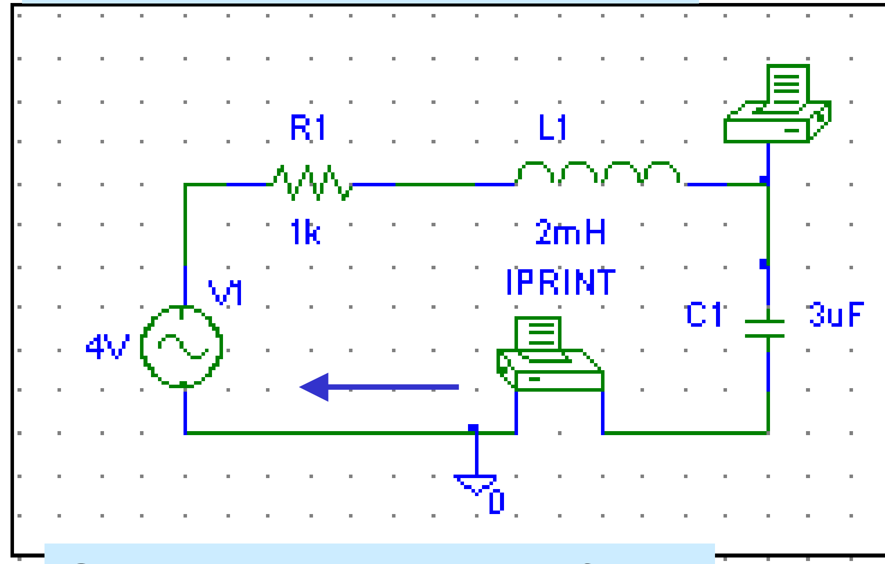
```
 y =
   Columns 1 through 4
    1.0000                  0                  0                  0
   -1.0000        1.0000 + 0.5000i         0 - 1.0000i           0
         0             0 - 1.0000i   1.5000 + 1.0000i            0
   -0.5000                  0                  0         1.5000 + 1.0000i
         0             0 + 0.5000i  -0.5000             -1.0000
   Column 5
         0
         0 + 0.5000i
   -0.5000
   -1.0000
    1.5000 + 0.5000i
```

Echo of Matrix

AC PSPICE ANALYSIS

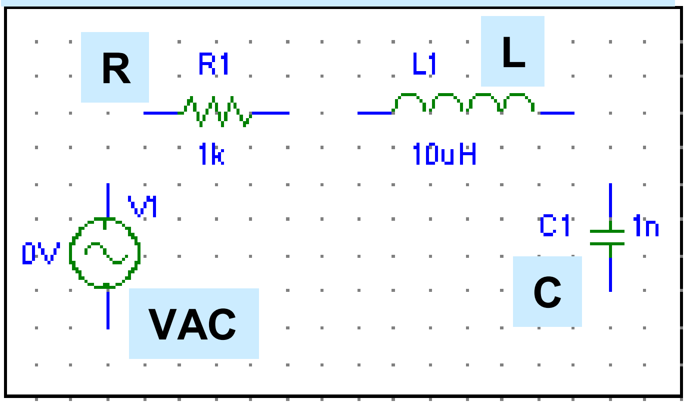


Circuit ready to be simulated

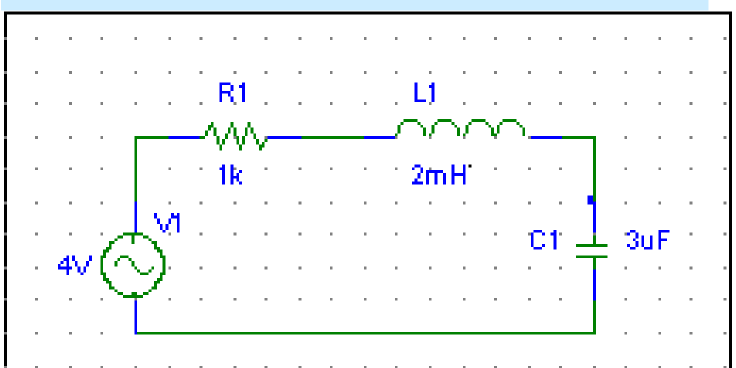


Ground set, meters specified

Select and place components



Wire and set correct attributes



```
****     AC ANALYSIS                              TEMPERATURE =   27.000 DEG C

************************************************************************
******
```

Results in output file

```
 FREQ         VM($N_0003)  VP($N_0003)


  6.000E+01    2.651E+00   -3.854E+01

**** 05/20/01 09:03:41 *********** Evaluation PSpice (Nov 1999)
**************

 * C:\ECEWork\IrwinPPT\ACSteadyStateAnalysis\Sec7p9Demo.sch


 ****     AC ANALYSIS                              TEMPERATURE =   27.000 DEG C


************************************************************************
******


 FREQ         IM(V_PRINT2)IP(V_PRINT2)


  6.000E+01    2.998E-03    5.146E+01
```

GEAUX