

# EE102 - Practice Final Exam

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## Rules:

- You have 3 hours.
  - Only this booklet and Two Sheets of notes may be on your desk. NOT allowed: lecture notes, homeworks, calculators,...
  - Answer each question in the space provided. EXPLAIN your reasoning. Simply writing down the answer is not adequate.
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## Problem 1 [15 pts]

In class we saw that the cascade of two linear time invariant (LTI) systems is also LTI. Now we ask:

- Is the cascade of two linear time varying (LTV) systems always LTV?
- Is the cascade of two time invariant (TI, not necessarily linear) systems always TI?
- Is the cascade of two nonlinear systems always nonlinear ?

For each case you must give either:

- a proof that the answer is affirmative.
- a counterexample showing it is not the case.

## Problem 2 [15 pts]

A linear, time invariant system has impulse response function given by

$$h(t) = a \delta(t) + b e^{-t}u(t) + cte^{-t}u(t)$$

where  $a, b, c$  are constants. We are given the following information:

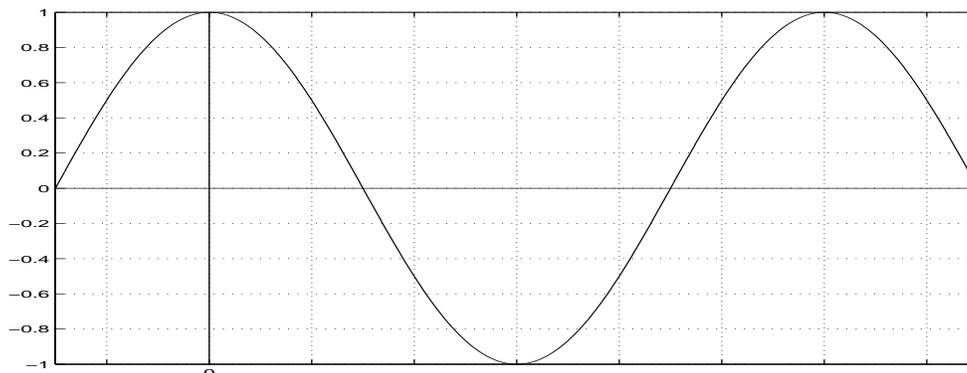
- When the input is  $x(t) \equiv 1$  for  $t \in (-\infty, \infty)$ , the output is the same as the input.
  - When the input is  $x(t) = \cos(t)$  for  $t \in (-\infty, \infty)$ , the output is zero.
- Find  $a, b, c$ .
  - Now let the input be  $x(t) = \cos(t)u(t)$ . Find the output.

### Problem 3 [20 pts]

Consider the three signals

$$x_1(t) = \cos(t); \quad x_2(t) = \cos\left(t - \frac{2\pi}{3}\right); \quad x_3(t) = \cos\left(t + \frac{2\pi}{3}\right).$$

- a) Sketch the signals in the plot below;  $x_1(t)$  has been provided for your convenience; you should specify the coordinates in the  $t$ -axis.



- b) Now let  $y(t) = \max\{x_1(t), x_2(t), x_3(t)\}$ ; in other words  $y(t)$  takes the maximum of the three signals at each instant in time. Sketch  $y(t)$  in a separate plot. What is the period of  $y(t)$ ?
- c) Find the mean square error  $\overline{\epsilon_0^2}$  resulting from approximating  $y(t)$  by a constant function.

### Problem 4 [15 pts]

We are given an LTI system with impulse response function

$$h(t) = \begin{cases} 1 - \frac{|t|}{\pi} & \text{if } |t| < \pi \\ 0 & \text{otherwise} \end{cases}$$

- a) Find the frequency response function  $H(i\omega)$ .
- b) We now apply to this system a periodic input, with period  $T$ . Discuss whether the following is true or false:  
*There exists a value of  $T$  such that for every periodic input of this period, the output is a constant function of time.*  
You should either show it's true and find an appropriate  $T$ , or show no such  $T$  exists.

### Problem 5 [20 pts]

a) Given a periodic function  $f(t)$  with Fourier series expansion

$$f(t) = \sum_{n=-\infty}^{\infty} F_n e^{in\omega_0 t}$$

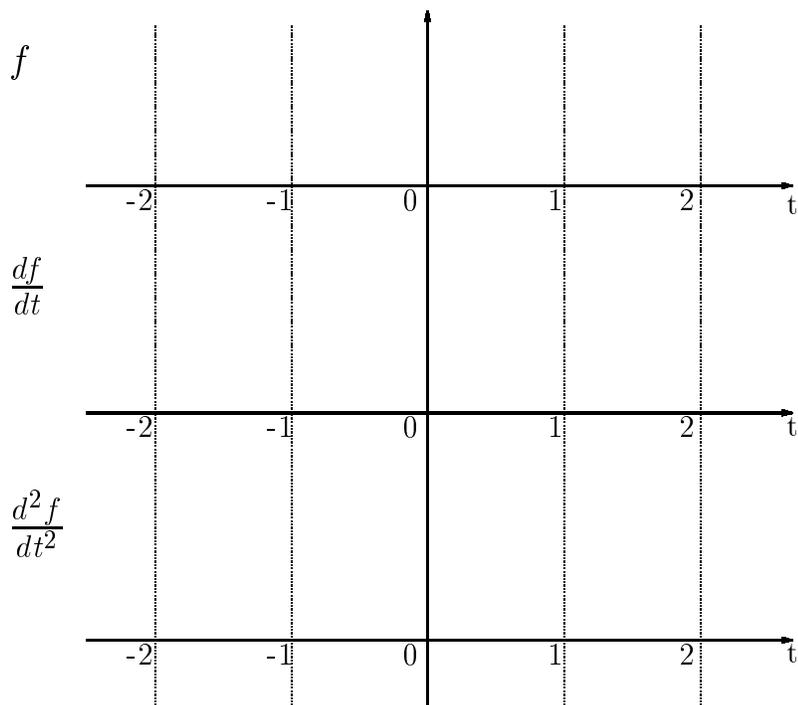
derive a formula for the Fourier series expansion of  $\frac{df}{dt}(t)$ .

b) Now consider  $f(t)$  of period  $T = 2$  and such that

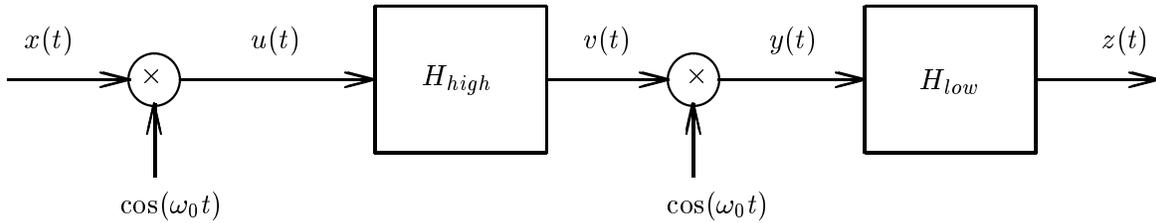
$$f(t) = \begin{cases} (t+1)^2 & \text{for } t \in [-1, 0] \\ (t-1)^2 & \text{for } t \in [0, 1] \end{cases}$$

Sketch  $f(t)$ ,  $\frac{df}{dt}(t)$  and  $\frac{d^2f}{dt^2}(t)$  in the space provided below.

c) Find the Fourier series expansions of  $f(t)$ ,  $\frac{df}{dt}(t)$  and  $\frac{d^2f}{dt^2}(t)$ .



**Problem 6 [15 pts]**



In the above system

- $H_{high}$  is an ideal high-pass filter with cutoff frequency  $\omega_0$ .
- $H_{low}$  is an ideal low-pass filter, also with cutoff frequency  $\omega_0$ .
- $u(t) = x(t) \cos(\omega_0 t)$  and  $y(t) = v(t) \cos(\omega_0 t)$ .
- $x(t)$  is band-limited to  $[-B, B]$ , as depicted in the figure below.  $X(0) = A$ .
- $\omega_0 > 2B$ .

Sketch the Fourier transforms  $U(i\omega)$ ,  $V(i\omega)$ ,  $Y(i\omega)$  and  $Z(i\omega)$ , and relate  $z(t)$  to  $x(t)$ . Justify your answer.

